

INTERNATIONAL STANDARD

**ISO/IEC
14496-3**

Third edition
2005-12-01

AMENDMENT 2
2006-03-15

Information technology — Coding of audio-visual objects —

Part 3: Audio

AMENDMENT 2: Audio Lossless Coding
(ALS), new audio profiles and BSAC
extensions

*Technologies de l'information — Codage des objets audiovisuels —
Partie 3: Codage audio*

*AMENDEMENT 2: Codage audio sans perte (ALS), nouveaux profils
audio et extensions BSAC*

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Reference number
ISO/IEC 14496-3:2005/Amd.2:2006(E)



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Published in Switzerland

Foreword

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Amendment 2 to ISO/IEC 14496-3:2005 was prepared by Joint Technical Committee ISO/IEC JTC 1, *Information technology*, Subcommittee SC 29, *Coding of audio, picture, multimedia and hypermedia information*.

This amendment specifies the Audio Lossless Coding (ALS) scheme. The amendment further defines a new profile, the High Efficiency AAC v2 Profile, that incorporates all the features of the High Efficiency AAC Profile and in addition the Parametric Stereo tool. The amendment also specifies the way in which the audio object type ER BSAC is extended to support multi-channel format, providing backward compatibility.

Information technology — Coding of audio-visual objects —

Part 3: Audio

AMENDMENT 2: Audio Lossless Coding (ALS), new audio profiles and BSAC extensions

In the Introduction, at the end of subclause "Lossless Audio Coding Tools", add:

MPEG-4 ALS (Audio Lossless Coding) provides lossless coding of digital audio signals. Input signals can be integer PCM data with 8 to 32-bit word length or 32-bit IEEE floating-point data. Up to 65536 channels are supported.

In Part 3: Audio, Subpart 1, in subclause 1.3 Terms and Definitions, add:

ALS: Audio Lossless Coding

and increase the index-number of subsequent entries.

In Part 3: Audio, Subpart 1, in subclause 1.5.1.1 Audio object type definition, replace table 1.1 with the table below:

Table 1.1 — Audio Object Type definition based on Tools/Modules

Object Type ID	Audio Object Type	gain control	block switching	window shapes - standard	window shapes – AAC LD	filterbank - standard	filterbank - SSR	TNS	LTP	intensity	coupling	frequency deomain prediction	PNS	MS	SIAQ	FSS	upsampling filter tool	quantisation&coding - AAC	quantisation&coding – TwinVQ	quantisation&coding - BSAC	AAC EFR Tools	ER payload syntax	EP Tool(1)	CELP	Silence Compression	HVXC	HVXC 4kbit/s VR	SA tools	SASBF	MIDI	HILN	TTSI	SBR	Layer-1	Layer-2	Layer-3	SSC (Transient, Sinusoid, Noise)	Parametric stereo	DST	ALS	Remark
0	Null																																								
1	AAC main	X	X	X	X	X	X	X	X	X	X	X	X	X	X		X																								
2	AAC LC	X	X	X	X	X	X	X	X	X	X	X	X	X	X		X																								
3	AAC SSR	X	X	X	X	X	X	X	X	X	X	X	X	X	X		X																								
4	AAC LTP	X	X	X	X	X	X	X	X	X	X	X	X	X	X		X																								
5	SBR																																								
6	AAC Scalable	X	X	X	X	X	X	X	X	X	X	X	X	X	X																										
7	TwinVQ	X	X	X	X	X	X	X	X	X	X	X	X	X	X		X																								
8	CELP																																								
9	HVXC																																								
10	(reserved)																																								
11	(reserved)																																								
12	TTSI																																								
13	Main synthetic																																								
14	Wavetable synthesis																																								
15	General MIDI																																								
16	Algorithmic Synthesis and Audio FX																																								
17	ER AAC LC	X	X	X	X	X	X	X	X	X	X	X	X	X	X		X																								
18	(reserved)																																								
19	ER AAC LTP	X	X	X	X	X	X	X	X	X	X	X	X	X	X		X																								
20	ER AAC scalable	X	X	X	X	X	X	X	X	X	X	X	X	X	X		X																								
21	ER TwinVQ	X	X	X	X	X	X	X	X	X	X	X	X	X	X		X																								
22	ER BSAC	X	X	X	X	X	X	X	X	X	X	X	X	X	X		X																								
23	ER AAC LD																																								
24	ER CELP																																								
25	ER HVXC																																								
26	ER HILN																																								
27	ER Parametric																																								
28	SSC																																								
29	PS																																								
30	(reserved)																																								
31	(escape)																																								
32	Layer-1																																								
33	Layer-2																																								
34	Layer-3																																								
35	DST																																								
36	ALS																																								
37 - 95	(reserved)																																								

In Part 3: Audio, Subpart 1, in subclause 1.5.1.2 Description, add:

1.5.1.2.30 ALS object type

The ALS object type is the counterpart of the Audio Lossless Coding (ALS) scheme and contains the corresponding ALS tools.

In Part 3: Audio, Subpart 1, replace Table 1.3 (Audio Profiles definition) with the following table:

Table 1.3 – Audio Profiles definition

Object Type ID	Audio Object Type	Main Audio Profile	Scalable Audio Profile	Speech Audio Profile	Synthetic Audio Profile	High Quality Audio Profile	Low Delay Audio Profile	Natural Audio Profile	Mobile Audio Internet-working Profile	AAC Profile	High Efficiency AAC Profile	High Efficiency AAC v2 Profile
0	Null											
1	AAC main	X						X				
2	AAC LC	X	X			X		X		X	X	X
3	AAC SSR	X						X				
4	AAC LTP	X	X			X		X				
5	SBR									X		X
6	AAC Scalable	X	X			X		X				
7	TwinVQ	X	X					X				
8	CELP	X	X	X		X	X	X				
9	HVXC	X	X	X				X	X			
10	(reserved)											
11	(reserved)											
12	TTSI	X	X	X	X		X	X				
13	Main synthetic	X			X							
14	Wavetable synthesis											
15	General MIDI											
16	Algorithmic Synthesis and Audio FX											
17	ER AAC LC					X		X	X			
18	(reserved)											
19	ER AAC LTP					X		X				
20	ER AAC Scalable					X		X	X			
21	ER TwinVQ							X	X			
22	ER BSAC							X	X			
23	ER AAC LD						X	X	X			
24	ER CELP					X	X	X				
25	ER HVXC						X	X				
26	ER HILN							X				
27	ER Parametric							X				
28	SSC											
29	PS										X	
30	(reserved)											
31	(escape)											
32	Layer-1											
33	Layer-2											
34	Layer-3											
35	DST											
36	ALS											

In Part 3: Audio, Subpart 1, subclause 1.5.2.3 (Levels within the profiles), add at the end:

- **Levels for the High Efficiency AAC v2 Profile**

Table 1.11A - Levels for the High Efficiency AAC v2 Profile

Level	Max. channels/ object	Max. AAC sampling rate, SBR not present [kHz]	Max. AAC sampling rate, SBR present [kHz]	Max. SBR sampling rate [kHz] (in/out)	Max. PCU	Max. RCU	Max. PCU HQ / LP SBR (Note 5)	Max. RCU HQ / LP SBR (Note 5)
1	NA	NA	NA	NA	NA	NA	NA	NA
2	2	48	24	24/48 (Note 1)	9	10	9	10
3	2	48	24/48 (Note 3)	48/48 (Note 2)	15	10	15	10
4	5	48	24/48 (Note 4)	48/48 (Note 2)	25	28	20	23
5	5	96	48	48/96	49	28	39	23

Note 1: A level 2 HE AAC v2 Profile decoder implements the baseline version of the parametric stereo tool. Higher level decoders shall not be limited to the baseline version of the parametric stereo tool.

Note 2: For level 3 and level 4 decoders, it is mandatory to operate the SBR tool in downsampled mode if the sampling rate of the AAC core is higher than 24kHz. Hence, if the SBR tool operates on a 48kHz AAC signal, the internal sampling rate of the SBR tool will be 96kHz, however, the output signal will be downsampled by the SBR tool to 48kHz.

Note 3: If Parametric Stereo data is present the maximum AAC sampling rate is 24kHz, if Parametric Stereo data is not present the maximum AAC sampling rate is 48kHz.

Note 4: For one or two channels the maximum AAC sampling rate, with SBR present, is 48kHz. For more than two channels the maximum AAC sampling rate, with SBR present, is 24kHz.

Note 5: The PCU/RCU number are given for a decoder operating the LP SBR tool whenever applicable.

A HE AAC v2 Profile decoder of a certain level shall operate the HQ SBR tool for streams containing Parametric Stereo data. For streams not containing Parametric Stereo data, the HE AAC v2 Profile decoder may operate the HQ SBR tool, or the LP SBR tool.

In Part 3: Audio, Subpart 1, subclause 1.5.2.4 (Table 1.12 - audioProfileLevelIndication Values), replace the row:

0x30-0x7F	reserved for ISO use	-
-----------	----------------------	---

with:

0x28	AAC Profile	L1
0x29	AAC Profile	L2
0x2A	AAC Profile	L4
0x2B	AAC Profile	L5
0x2C	High Efficiency AAC Profile	L2
0x2D	High Efficiency AAC Profile	L3
0x2E	High Efficiency AAC Profile	L4
0x2F	High Efficiency AAC Profile	L5
0x30	High Efficiency AAC v2 Profile	L2
0x31	High Efficiency AAC v2 Profile	L3
0x32	High Efficiency AAC v2 Profile	L4
0x33	High Efficiency AAC v2 Profile	L5
0x34-0x7F	reserved for ISO use	-

In Part 3: Audio, Subpart 1, in subclause 1.6.2.1 *AudioSpecificConfig*, replace table 1.13 with the table below:

Table 1.13 — Syntax of *AudioSpecificConfig*()

Syntax	No. of bits	Mnemonic
<pre> AudioSpecificConfig () { audioObjectType = GetAudioObjectType(); samplingFrequencyIndex; if (samplingFrequencyIndex == 0xf) { samplingFrequency; } channelConfiguration; sbrPresentFlag = -1; psPresentFlag = -1; if (audioObjectType == 5 audioObjectType == 29) { extensionAudioObjectType = 5; sbrPresentFlag = 1; if (audioObjectType == 29) { psPresentFlag = 1; } extensionSamplingFrequencyIndex; if (extensionSamplingFrequencyIndex == 0xf) { extensionSamplingFrequency; } audioObjectType = GetAudioObjectType(); } else { extensionAudioObjectType = 0; } switch (audioObjectType) { case 1: case 2: case 3: case 4: case 6: case 7: case 17: case 19: case 20: case 21: case 22: case 23: GASpecificConfig(); break; case 8: CelpSpecificConfig(); break; case 9: HvxcSpecificConfig(); break; case 12: TTSSpecificConfig(); break; } } </pre>	4 24 4 4 24	bslbf uimsbf bslbf uimsbf uimsbf

```

case 13:
case 14:
case 15:
case 16:
    StructuredAudioSpecificConfig();
    break;
case 24:
    ErrorResilientCelpSpecificConfig();
    break;
case 25:
    ErrorResilientHvxcSpecificConfig();
    break;
case 26:
case 27:
    ParametricSpecificConfig();
    break;
case 28:
    SSCSpecificConfig();
    break;
case 32:
case 33:
case 34:
    MPEG_1_2_SpecificConfig();
    break;
case 35:
    DSTSpecificConfig();
    break;
case 36:
    ALSSpecificConfig();
    break;
default:
    /* reserved */
}
switch (audioObjectType) {
case 17:
case 19:
case 20:
case 21:
case 22:
case 23:
case 24:
case 25:
case 26:
case 27:
    epConfig;
    if (epConfig == 2 || epConfig == 3) {
        ErrorProtectionSpecificConfig();
    }
    if (epConfig == 3) {
        directMapping;
        if (!directMapping) {
            /* tbd */
        }
    }
}
if (extensionAudioObjectType != 5 && bits_to_decode() >= 16) {
    syncExtensionType;
    if (syncExtensionType == 0x2b7) {
        extensionAudioObjectType = GetAudioObjectType();
    }
}

```

2

bslbf

1

bslbf

11

bslbf

if (extensionAudioObjectType == 5) {			
sbrPresentFlag;	1	uimsbf	
if (sbrPresentFlag == 1) {			
extensionSamplingFrequencyIndex;	4	uimsbf	
if (extensionSamplingFrequencyIndex == 0xf) {			
extensionSamplingFrequency;	24	uimsbf	
}			
if (bits_to_decode() >= 12) {			
syncExtensionType;	11	bslbf	
if (syncExtensionType == 0x548) {			
psPresentFlag;	1	uimsbf	
}			
}			
}			
}			
}			

In Part 3: Audio, Subpart 1, in subclause 1.6.2.1 *AudioSpecificConfig*, add:

1.6.2.1.12 ALSSpecificConfig

Defined in ISO/IEC 14496-3 subpart 11.

In Part 3: Audio, Subpart 1, in subclause 1.6.2.2.1 Overview, replace table 1.15 by the following table:

Table 1.15 – Audio Object Types

Audio Object Type	Object Type ID	definition of elementary stream payloads and detailed syntax	Mapping of audio payloads to access units and elementary streams
AAC MAIN	1	ISO/IEC 14496-3 subpart 4	see subclause 1.6.2.2.1.2
AAC LC	2	ISO/IEC 14496-3 subpart 4	see subclause 1.6.2.2.1.2
AAC SSR	3	ISO/IEC 14496-3 subpart 4	see subclause 1.6.2.2.1.2
AAC LTP	4	ISO/IEC 14496-3 subpart 4	see subclause 1.6.2.2.1.2
SBR	5	ISO/IEC 14496-3 subpart 4	
AAC scalable	6	ISO/IEC 14496-3 subpart 4	see subclause 1.6.2.2.1.3
TwinVQ	7	ISO/IEC 14496-3 subpart 4	
CELP	8	ISO/IEC 14496-3 subpart 3	
HVXC	9	ISO/IEC 14496-3 subpart 2	
TSI	12	ISO/IEC 14496-3 subpart 6	
Main synthetic	13	ISO/IEC 14496-3 subpart 5	
Wavetable synthesis	14	ISO/IEC 14496-3 subpart 5	
General MIDI	15	ISO/IEC 14496-3 subpart 5	
Algorithmic Synthesis and Audio FX	16	ISO/IEC 14496-3 subpart 5	
ER AAC LC	17	ISO/IEC 14496-3 subpart 4	see subclause 1.6.2.2.1.4
ER AAC LTP	19	ISO/IEC 14496-3 subpart 4	see subclause 1.6.2.2.1.4
ER AAC scalable	20	ISO/IEC 14496-3 subpart 4	see subclause 1.6.2.2.1.4
ER Twin VQ	21	ISO/IEC 14496-3 subpart 4	
ER BSAC	22	ISO/IEC 14496-3 subpart 4	

ER AAC LD	23	ISO/IEC 14496-3 subpart 4	see subclause 1.6.2.2.2.1.4
ER CELP	24	ISO/IEC 14496-3 subpart 3	
ER HVXC	25	ISO/IEC 14496-3 subpart 2	
ER HILN	26	ISO/IEC 14496-3 subpart 7	
ER Parametric	27	ISO/IEC 14496-3 subpart 2 and 7	
SSC	28	ISO/IEC 14496-3 subpart 8	
PS	29	ISO/IEC 14496-3 subpart 8	
(reserved)	30		
(escape)	31		
Layer-1	32	ISO/IEC 14496-3 subpart 9	
Layer-2	33	ISO/IEC 14496-3 subpart 9	
Layer-3	34	ISO/IEC 14496-3 subpart 9	
DST	35	ISO/IEC 14496-3 subpart 10	
ALS	36	ISO/IEC 14496-3 subpart 11	

In Part 3: Audio, Subpart 1, under 1.6.3 Semantics, after 1.6.3.13 extensionAudioObjectType add:

1.6.3.14 psPresentFlag

A one bit field indicating the presence or absence of Parametric Stereo data. The value –1 indicates that the psPresentFlag was not conveyed in the AudioSpecificConfig(). In this case, a High Efficiency AAC v2 Profile decoder shall support implicit signaling (see subclause 1.6.6).

In Part 3: Audio, Subpart 1, after 1.6.5 Signaling of SBR, add the following subclause:

1.6.6 Signaling of Parametric Stereo (PS)

1.6.6.1 Generating and Signaling HE AAC + PS Content

The PS tool in combination with the HE AAC coder enables good stereo quality at very low bitrates. At the same time it allows for compatibility with existing HE AAC-only decoders. However, the output from a HE AAC decoder will only be mono for a HE AAC v2 stream carrying PS data.

Therefore, depending on the application, a content provider or content creator may want to choose between the two alternatives given below. In general, the PS data is always embedded in the HE AAC stream in a HE AAC compatible way (in the sbr_extension element), and PS is a pure post processing step in the decoder. Therefore, compatibility can be achieved. However, by means of different signaling the content creator can select between the full-quality mode and the backward compatibility mode as outlined in 1.6.6.1.1 and 1.6.6.1.2.

For the hierarchical profiles, a profile higher in the profile hierarchy is of course able to decode the content of a profile lower in the profile hierarchy. In Figure 1.0A the hierarchical structure of the AAC, HE AAC and HE AAC v2 Profile is displayed. The figure shows that a HE AAC Profile decoder is fully capable of decoding any AAC-Profile stream, given that the HE AAC Profile decoder is of the same or a higher level as indicated in the AAC Profile stream. Similarly the HE AAC v2 decoder can handle all HE AAC Profile streams as well as all AAC Profile streams.

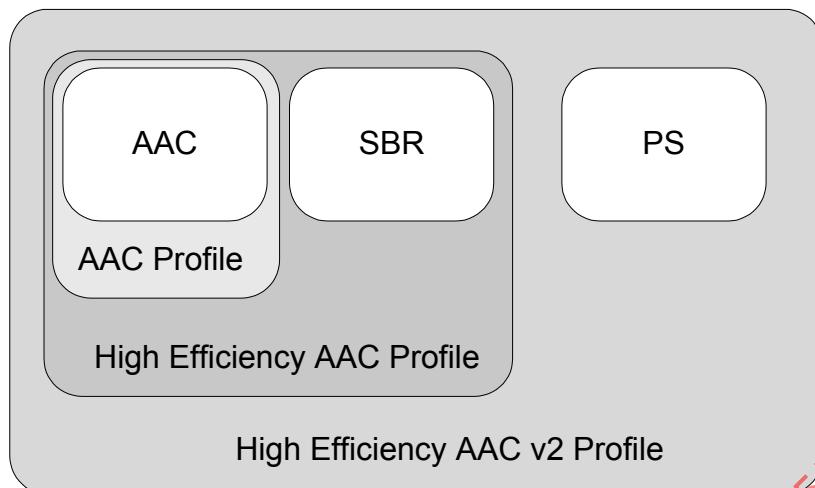


Figure 1.0A – Hierarchical structure of AAC, HE AAC and HE AAC v2 Profile, and compatibility between them.

1.6.6.1.1 Ensuring Full Audio Quality of AAC+SBR+PS for the Listener

To ensure that listeners get the full audio quality of AAC+SBR+PS, the stream should indicate the HE AAC v2 Profile and use the explicit, hierarchical signaling (signaling 2.A. as described below), so that it is played by HE AAC v2 Profile decoders, i.e., PS capable decoders. With regard to HE AAC-only streams or AAC-only streams, an HE AAC v2 Profile decoder will decode all HE AAC Profile streams and AAC Profile streams of the appropriate level, as the HE AAC v2 Profile is a superset of the HE AAC Profile and the AAC Profile.

1.6.6.1.2 Achieving Backward Compatibility with Existing HE AAC and AAC Decoders

The aim of this mode is to get all AAC-based and HE AAC-based decoders to play the stream, even if they do not support the PS tool. Compatible streams can be created using the following two signaling methods:

- indicate a profile containing SBR (e.g. the HE AAC Profile), but not the HE AAC v2 Profile, and use the explicit backward compatible signalling (2.B. as described below). This method is recommended for all MPEG-4 based systems in which the length of the `AudioSpecificConfig()` is known in the decoder. As this is not the case for LATM with `audioMuxVersion==0` (see clause 1.7), this method cannot be used for LATM with `audioMuxVersion==0`. In explicit backward compatible signaling, PS-specific configuration data is added at the end of the `AudioSpecificConfig()`. Decoders that do not know about PS will ignore these parts, while HE AAC v2 Profile decoders will detect its presence and configure the decoder accordingly.
- indicate a profile containing SBR (e.g. the HE AAC Profile), but not the HE AAC v2 Profile, and use implicit signalling. In this mode, there is no explicit indication of the presence of PS data. Instead, HE AAC v2 Profile decoders shall open two output channels for a stream containing SBR data with `channelConfiguration==1`, i.e., a mono stream using a single channel element, and check the presence of PS data while decoding the stream and use the PS tool if PS data is found. This is possible because PS can be decoded without PS-specific configuration data if a certain way of handling decoder number of output channels is obeyed, as described below for HE AAC v2 Profile decoders.

Both methods lead to the result that, provided that the profile indication indicates a profile supported by the decoder, the AAC+SBR part of an AAC+SBR+PS streams will be decoded by HE AAC-only decoders, and the AAC part of an AAC+SBR+PS stream will be decoded by AAC-only decoders. HE AAC v2 decoders will detect the presence of PS and decode the full quality AAC+SBR+PS stream.

1.6.6.2 Implicit and Explicit Signaling of Parametric Stereo

This subclause outlines the different signaling methods of PS, and the decoder behavior for different types of signaling.

There are several ways to signal the presence of PS data:

1. **implicit signaling:** If `bs_extension_id` equals `EXTENSION_ID_PS`, PS data is present in the `sbr_extension` element, and this implicitly signals the presence of PS data. The ability to detect and decode implicitly signaled PS is mandatory for all High Efficiency AAC v2 Profile (HE AAC v2 Profile) decoders.
2. **explicit signaling:** The presence of PS data is signaled explicitly by means of the PS Audio Object Type and the `psPresentFlag` in the `AudioSpecificConfig()`. When explicit signaling of PS is used, implicit signaling of PS shall not occur. Two different types of explicit signaling are available:
 - 2.A. **hierarchical signaling:** If the first `audioObjectType` (AOT) signaled is the PS AOT, the `extensionAudioObjectType` is set to SBR, and a second audio object type is signaled which indicates the underlying audio object type. This signaling method is not backward compatible. This method may be needed in systems that do not convey the length of the `AudioSpecificConfig()`, such as LATM with `audioMuxVersion==0`, and content authors are encouraged to use it only when thus needed.
 - 2.B. **backward compatible signaling:** If the `extensionAudioObjectType` SBR is signaled at the end of the `AudioSpecificConfig()`, a `psPresentFlag` is transmitted at the end of the backward compatible explicit SBR signaling, indicating the presence or absence of PS data. This method shall only be used in systems that convey the length of the `AudioSpecificConfig()`. Hence, it shall not be used for LATM with `audioMuxVersion==0`.

For all types of parametric stereo signaling, the `channelConfiguration` in the `audioSpecificConfig` indicates the number of channels of the underlying AAC coded stream. Hence, if parametric stereo data is available, the `channelConfiguration` will be one, indicating a single channel element, while the parametric stereo tool will produce two output channels based on the single channel element and the parametric stereo data.

Table 1.22A shows the decoder behavior depending on profile and audio object type indication when implicit or explicit signaling is used.

Table 1.22A – PS Signaling and Corresponding Decoder Behavior

Profile indication	Bitstream characteristics			Decoder behavior	
	PS signaling	psPresent Flag	raw_data_block	HE AAC Profile Decoders	HE AAC v2 Profile Decoders
High Efficiency AAC Profile	signaling 1, implicit signaling (first AOT != PS)	-1	AAC+SBR	Play AAC+SBR	Play AAC+SBR (Note 1)
			AAC+SBR+PS	Play AAC+SBR	Play at least AAC+SBR, should play AAC+SBR+PS (Note 1)
	signaling 2.B, backwards compatible explicit signaling (second AOT == SBR)	0	AAC+SBR	Play AAC+SBR	Play AAC+SBR (Note 2)
		1	AAC+SBR+PS	Play AAC+SBR	Play at least AAC+SBR, should play AAC+SBR+PS (Note 3)
High Efficiency AAC v2 Profile	signaling 2.A, non-backwards compatible signaling (first AOT == PS)	1	AAC+SBR+PS	Undefined	Play AAC+SBR+PS (Note 3)
	signaling 2.B, backwards compatible signaling (second AOT == SBR)	1	AAC+SBR+PS	Undefined	Play AAC+SBR+PS (Note 3)
<p>Note 1: Implicit signaling, assume the presence of PS data in the payload, giving two output channels for a single channel element.</p> <p>Note 2: Explicitly signals that there is no PS data, hence no implicit signaling is present.</p> <p>Note 3: Number of output channels is two for a single channel element containing AAC+SBR+PS data.</p>					

The upper part of Table 1.22A displays bitstream characteristics and decoder behavior if the profile indication is the High Efficiency AAC Profile. The lower part displays bitstream characteristics and decoder behavior if the profile indication is the High Efficiency AAC v2 Profile.

1.6.6.3 HE AAC v2 Profile Decoder Behavior in Case of Implicit Signaling

If the presence of PS data is backward compatible implicitly signaled (signaling 1, in the list above) the first AudioObjectType signaled is not the PS AOT, and the psPresentFlag is not read from the AudioSpecificConfig(). Hence, the psPresentFlag is set to -1, indicating that implicit signaling of parametric stereo may occur.

Since a received mono stream will result in a stereo output if Parametric Stereo data is present in the stream, the HE AAC v2 Profile decoder shall assume that PS data is available and decide the number of output channels to be two for a single channel element containing SBR data, and thus also possibly PS data. If no PS data is found the mono output shall be mapped to the two opened channels for every single channel element.

1.6.6.4 HE AAC v2 Profile Decoder Behavior in Case of Explicit Signaling

If the presence of PS data is explicitly signaled (signaling 2, in the list above) the presence of PS data is backward compatible explicitly signaled (signaling 2.B) or non-backward compatible explicitly signaled (signaling 2.A).

For the backward compatible explicit signaled (signaling 2.B) the extensionAudioObjectType signaled is the SBR AOT. The explicit signaling of PS is done by means of the psPresentFlag that can be either zero or one.

If the psPresentFlag is zero, this indicates that PS data is not present, and hence the HE AAC v2 Profile decoder should not make assumptions on the number of output channels in anticipation of PS data (as in case of implicit signaling of PS) and instead employ the original channelConfiguration. If the psPresentFlag is one, PS data is present and the HE AAC v2 Profile decoder shall operate the PS Tool.

For the non-backward compatible explicit signaling of PS (signaling 2.A) the first AudioObjectType signaled is the PS AOT. The extensionAudioObjectType is assigned the SBR AOT. For this hierarchical explicit signaling, the psPresentFlag is set to one if the first signaled AOT is the PS AOT. The psPresentFlag is not transmitted and hence it is not possible to explicitly signal the absence of implicit signaling. Hence, for the hierarchical explicit signaling of parametric stereo, PS data is always present and the HE AAC v2 Profile decoder shall operate the PS Tool.

In Part 3: Audio, Subpart 4, in subclause 4.4.2.6 Payloads for the audio object type ER BSAC, replace table 4.33 bsac_raw_data_block with the following table:

Table 4.33 – Syntax of bsac_raw_data_block()

Syntax	No. of bits	Mnemonic
<pre>bsac_raw_data_block() { bsac_base_element(); layer=slayer_size; while(data_available() && layer<(top_layer+slayer_size)) { bsac_layer_element(layer); layer++; } byte_alignment(); if (data_available()) { zero_code syncword while(data_available()) extended_bsac_raw_data_block(); } }</pre>	32 8	bslbf bslbf

In Part 3: Audio, Subpart 4, in subclause 4.4.2.6 Payloads for the audio object type ER BSAC, after Table 4.43 Syntax of *bsac_spectral_data*, add the following two tables:

Table 4.35 – Syntax of *extended_bsac_raw_data_block()*

Syntax	No. of bits	Mnemonic
<pre>extended_bsac_raw_data_block() { extended_bsac_base_element(); layer=slayer_size; while(data_available() && layer<(top_layer+slayer_size)) { bsac_layer_element(layer); layer++; } byte_alignment(); }</pre>		

Table 4.36 – Syntax of *extended_bsac_base_element()*

Syntax	No. of bits	Mnemonic
extended_bsac_base_element()		
{		
element_length	11	uimbf
channel_configuration_index	3	uimbf
reserved_bit	1	uimbf
bsac_header();		
general_header();		
byte_alignment();		
for (slayer = 0; slayer < slayer_size; slayer++) bsac_layer_element(slayer);		
}		

In Part 3: Audio, Subpart 4, under Bitstream elements in subclause 4.5.2.6.2.1 Definitions, replace *bsac_raw_data_block* with the following:

bsac_raw_data_block()

block of raw data that contains coded audio data, related information and other data. A *bsac_raw_data_block()* basically consists of *bsac_base_element()* and several *bsac_layer_element()*. There exists a module that determines whether the BSAC bitstream has an extended part.

In Part 3: Audio, Subpart 4, under Bitstream elements in subclause 4.5.2.6.2.1 Definitions, after *bsac_raw_data_block*, add the following:

zero_code

32-bit zero values in order to terminate the arithmetic decoding for the stereo part.

syncword

a eight bit code that identifies the start of the extended part. The bit string '1111 1111'.

In Part 3: Audio, Subpart 4, under Bitstream elements in subclause 4.5.2.6.2.1 Definitions, replace header_length with the following:

header_length

the length of the headers including frame_length, bsac_header() and general_header() in bytes. The actual length is (header_length+7) bytes. However if header_length is 0, it represents that the actual length is smaller than or equal to 7 bytes. And if header_length is 15, it represents that the actual length is larger than or equal to (15+7) bytes and should be calculated through the decoding of the headers. In case of extended_bsac_base_element(), header_length includes element_length, channel_configuration_index, reserved_bit, bsac_header and general_header().

In Part 3: Audio, Subpart 4 under Bitstream elements in subclause 4.5.2.6.2.1 Definitions, after bsac_spectral_data, add the following:

extended_bsac_raw_data_block()

block of raw data that contains coded audio data, related information and other data for the extended part. A extended_bsac_raw_data_block() basically consists of extended_bsac_base_element() and several bsac_layer_element().

extended_bsac_base_element()

syntactic element of the base layer bitstream containing coded audio data, related information and other data for the extended part of BSAC.

element_length

the length of the extended_bsac_raw_data_block() in bytes. This is used for proper arithmetic decoding.

channel_configuration_index

a three bit field that indicates the audio output channel configuration in the extended part. Each index specifies the number of channels given the channel to speaker mapping.

Table 4.68 – channel_configuration_index

Index	channel to speaker mapping	number of channels (nch)
0	center front speaker	1
1	left, right front speakers	2
2	rear surround speakers	1
3	left surround, right surround rear speakers	2
4	front low frequency effects speaker	1
5	left, right outside front speakers	2
6-7	reserved	-

reserved bit

bit reserved for future use

In Part 3: Audio, Subpart 4, after subclause 4.5.2.6.2.13 Reconstruction of the decoded sample from bit-sliced data, add the subclause below:

4.5.2.6.2.2.14 Decoding the extended part

The structure of the extended part of BSAC is a simple replica of mono or stereo BSAC bitstream. New functions called extended_bsac_raw_data_block and extended_bsac_base_element are added for the extended BSAC.

4.5.2.6.2.2.14.1 extended_bsac_raw_data_block

An extended_bsac_raw_data_block also has the layered structure as bsac_raw_data_block. In case where data is still available after decoding the stereo part, **zero_code** and **syncword** are parsed. **zero_code** is used for the arithmetic termination of stereo part, and **syncword** is for the proper decoding of extended part.

4.5.2.6.2.2.14.2 extended_bsac_base_element

An extended bsac_base_element consists of **element_length**, **channel_configuration_index**, **reserved_bit**, bsac_header, general_header and bsac_layer_element. For the stereo part, the value of *nch* is obtained from **channelConfiguration** in Table 1.8 (Syntax of AudioSpecificConfig) and it is limited to either 1 or 2 (left and right front speakers). For the extended part, the parameter, *nch*, is concerned with the rest of speakers, and the exact value is determined by **channel_configuration_index** specified in Table 4.68. Each index indicates the number of channels given the channel to speaker mapping.

In Part 3: Audio, Subpart 4, at the end of subclause 4.B.17.8 Payload transmitted over Elementary Stream bit-sliced data, add the following subclause:

4.B.17.8.1 The functionality of fine-grain scalability in extended or multi-channel data

When the BSAC data extends to multi-channel data, each ES consists of large-step layers for a certain channel element. To provide the functionality of fine-grain scalability in the multi-channel data, one might use *streamPriority* specified in the ES descriptor in ISO/IEC 14496-1:2004. The values of *streamPriority* are assigned to elementary streams according to the priority of channel elements. Different numbers of layers per channel element can be truncated, because the extended BSAC bitstream consists of separate channel elements. The values of *streamPriority* and the number of layers to be truncated per channel element depend on application scenarios.

In Part 3: Audio, Subpart 8, in clause 8.A.1, replace:

The usage of this parametric stereo extension to HE AAC is signalled implicitly in the bitstream. Hence, if

with:

The usage of this parametric stereo extension to HE AAC is signalled either implicitly by the presence of parametric stereo data in the bitstream, or explicitly by signalling the corresponding AudioObjectType in the audioSpecificConfig. Hence, implicit signalling requires that, if

Create Part 3: Audio, Subpart 11:

Subpart 11: Technical description of Audio Lossless Coding for lossless coding of audio signals

11.1 Scope

This subpart of ISO/IEC 14496-3 describes the MPEG-4 Audio Lossless Coding (ALS) algorithm for lossless coding of audio signals.

MPEG-4 ALS is a lossless compression scheme for digital audio data, i.e. the decoded data is a bit-identical reconstruction of the original input data. Input signals can be integer PCM data with 8 to 32-bit word length or 32-bit IEEE floating-point data. MPEG-4 ALS provides a wide range of flexibility in terms of compression-complexity trade-off, since the combination of several tools allows for the definition of compression levels with different complexities.

11.2 Technical Overview

11.2.1 Encoder and Decoder Structure

The basic structure of the ALS encoder and decoder is shown in Figure 11.1.

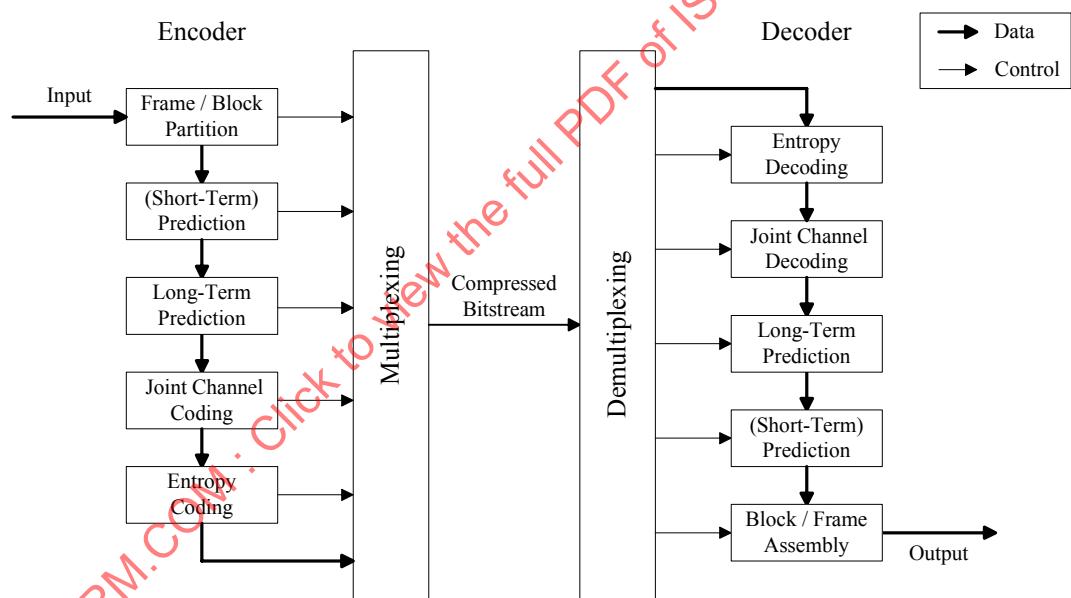


Figure 11.1 – Block diagram of the ALS encoder and decoder

The input audio data is partitioned into frames. Within a frame, each channel can be further subdivided into blocks of audio samples for further processing (*block switching*, see subclause 11.6.2). For each block, a prediction residual is calculated using short-term *prediction* (see subclauses 11.6.3 and 11.6.5) and optionally *long-term prediction* (LTP, see subclause 11.6.4). Inter-channel redundancy can be removed by *joint channel coding*, using either *difference coding of channel pairs* (see subclause 11.6.7) or *multi-channel coding* (MCC, see subclause 11.6.8). The remaining prediction residual is finally *entropy coded* (see subclause 11.6.6).

The encoder generates bitstream information allowing for random access at intervals of several frames. The encoder can also provide a CRC checksum, which the decoder may use to verify the decoded data.

11.2.2 Floating-Point Extensions

In addition to integer audio signals, MPEG-4 ALS also supports lossless compression of audio signals in the IEEE 32-bit floating-point format. The floating-point sequence is modeled by the sum of an integer sequence multiplied by a constant (ACF: Approximate Common Factor) and a residual sequence. The integer sequence is compressed using the basic ALS tools for integer data, while the residual sequence is separately compressed by the masked Lempel-Ziv tool. A detailed description of the floating-point extensions can be found in subclause 11.6.9.

11.3 Terms and Definitions

11.3.1 Definitions

The following definitions and abbreviations are used in this document.

Frame	Segment of the audio signal (containing all channels).
Block	Segment of one audio channel.
Sub-block	Subpart of a block that uses the same entropy coding parameters.
Random Access Frame	Frame that can be decoded without decoding previous frames.
Residual	Prediction error, i.e. original minus predicted signal.
Predictor/Prediction Filter	Linear FIR filter which computes an estimate of the input signal using previous samples.
Prediction order	Order of the prediction filter (number of predictor coefficients).
LPC coefficients	Coefficients of the direct form prediction filter.
Parcor coefficients	Parcor representation of the predictor coefficients.
Quantized coefficients	Quantized parcor coefficients.
LTP	Long-term prediction.
Rice code	Also known as Golomb-Rice code. In this document the short form is used.
BGMC	Block Gilbert-Moore Code (also known as Elias-Shannon-Fano code).
CRC	Cyclic Redundancy Check.
LPC	Linear Predictive Coding.
PCM	Pulse Code Modulation.
Mantissa	Fractional part of floating-point data
Exponent	Exponential part of floating-point data
ACFC	Approximate Common Factor Coding
Masked-LZ	Masked Lempel-Ziv Coding
MCC	Multi-Channel Coding
MSB	Most significant bit
LSB	Least significant bit

11.3.2 Mnemonics

uimsbf	Unsigned integer, most significant bit first
simsbf	Signed integer, most significant bit first
bslbf	Bit string, left bit first, where "left" is the order in which bits are written
IEEE32	IEEE 32-bit floating-point data (4 bytes), most significant bit first

The mnemonics Rice code and BGMC indicate that variable length codewords are used, which are described in subclause 11.6.6.

11.3.3 Data Types

The following data types are used in the pseudo code sections:

INT64	64-bit signed integer (two's complement)
long	32-bit signed integer (two's complement)
short	16-bit signed integer (two's complement)

If "unsigned" is added in front of the data type, then the type is unsigned instead of signed.

11.4 Syntax

11.4.1 Decoder Configuration

Table 11.1 – Syntax of ALSSpecificConfig

Syntax	No. of bits	Mnemonic
ALSSpecificConfig()		
{		
samp_freq;	32	uimsbf
samples;	32	uimsbf
channels;	16	uimsbf
file_type;	3	uimsbf
resolution;	3	uimsbf
floating;	1	uimsbf
msb_first;	1	uimsbf
frame_length;	16	uimsbf
random_access;	8	uimsbf
ra_flag;	2	uimsbf
adapt_order;	1	uimsbf
coef_table;	2	uimsbf
long_term_prediction;	1	uimsbf
max_order;	10	uimsbf
block_switching;	2	uimsbf
bgmc_mode;	1	uimsbf
sb_part;	1	uimsbf
joint_stereo;	1	uimsbf
mc_coding;	1	uimsbf
chan_config;	1	uimsbf
chan_sort;	1	uimsbf
crc_enabled;	1	uimsbf
RLSLMS	1	uimsbf

(reserved)	5		
aux_data_enabled;	1	uimsbf	
if (chan_config) {			
chan_config_info;	16	uimsbf	
}			
if (chan_sort) {			
for (c = 0; c < channels; c++)	1..16	uimsbf	
chan_pos[c];			
}			
byte_align;			
header_size;	16	uimsbf	
trailer_size;	16	uimsbf	
orig_header[];	header_size * 8	bslbf	
orig_trailer[];	trailer_size * 8	bslbf	
if (crc_enabled) {			
crc;	32	uimsbf	
}			
if ((ra_flag == 2) && (random_access > 0)) {			
for (f = 0; f < ((samples-1) / (frame_length+1)) + 1; f++) {	32	uimsbf	
ra_unit_size[f]			
}			
}			
if (aux_data_enabled) {			
aux_size;	16	uimsbf	
aux_data[];	aux_size * 8	bslbf	
}			

11.4.2 Bitstream Payloads

Table 11.2 – Syntax of top level payload (frame_data)

Syntax	No. of bits	Mnemonic
frame_data()		
{		
if ((ra_flag == 1) && (frame_id % random_access == 0)) {		
ra_unit_size	32	uimsbf
}		
if (mc_coding && joint_stereo) {		
js_switch;	1	uimsbf
byte_align;		
}		
if (!mc_coding js_switch) {		
for (c = 0; c < channels; c++) {		
if (block_switching) {		
bs_info;	8,16,32	uimsbf
}		
if (independent_bs) {		
for (b = 0; b < blocks; b++) {		
block_data(c);		
}		
}		
else{		
for (b = 0; b < blocks; b++) {		
block_data(c);		
block_data(c+1);		
}		
c++;		

<pre> } } else{ if (block_switching) { bs_info; } for (b = 0; b < blocks; b++) { for (c = 0; c < channels; c++) { block_data(c); channel_data(c); } } if (floating) { num_bytes_diff_float; diff_float_data(); } } </pre>	8,16,32	uimsbf
	32	uimsbf

Note: If joint_stereo is off, or if c is the last channel, independent_bs is true by default. If joint_stereo is on, independent_bs is false by default, but if block_switching is on as well, the independent_bs flag is explicitly signaled as the first bit of a channel pair's bs_info field (see subclause 11.6.2). The frame_id field indicates the consecutive frame number, starting at 0 for the first frame.

Table 11.3 – Syntax of block_data

Syntax	No. of bits	Mnemonic
block_data()		
{		
block_type;	1	uimsbf
if (block_type == 0) {		
const_block;	1	uimsbf
js_block;	1	uimsbf
(reserved)	5	
if (const_block == 1) {		
{		
if (resolution == 8) {		
const_val;	8	simsbf
}		
else if (resolution == 16) {		
const_val;	16	simsbf
}		
else if (resolution == 24) {		
const_val;	24	simsbf
}		
else {		
const_val;	32	simsbf
}		
}		
}		
else {		
js_block;	1	uimsbf
if ((bgmc_mode == 0) && (sb_part == 0) {		
sub_blocks = 1;		
}		
else if ((bgmc_mode == 1) && (sb_part == 1) {		
ec_sub;	2	uimsbf
sub_blocks = 1 << ec_sub;		
}		

<pre> for (n = k * sb_length; n < (k+1) * sb_length; n++) { msb[n]; } } for (n = start; n < sb_length; n++) { if (msb[n] != tail_code) { lsb[n]; } else { tail[n]; } } for (k=1; k < sub_blocks; k++) { for (n = k * sb_length; n < (k+1) * sb_length; n++) { if (msb[n] != tail_code) { lsb[n]; } else { tail[n]; } } } else { for (n = start; n < block_length; n++) { res[n]; } } } if (RLSLMS) { RLSLMS_extension_data() } } </pre>	varies	BGMC
	varies	uimsbf
	varies	Rice code
	varies	uimsbf
	varies	Rice code
	varies	Rice code
	varies	Rice code

Note: random_access_block is true if the current block belongs to a random access frame (frame_id % random_access == 0) and is the first (or only) block of a channel in this frame.

Table 11.4 – Syntax of channel_data

Syntax	No. of bits	Mnemonic
channel_data(c)		
{		
for(;;) {		
stop_flag,	1	uimsbf
if (stop_flag == 1) {		
break;		
}		
master_channel_index;	1..16	uimsbf
if (c != master_channel_index) {		
time_difference_flag	1	uimsbf
if (time_difference_flag == 0) {		
weighting_factor [0]	varies	Rice code
weighting_factor [1]	varies	Rice code
weighting_factor [2]	varies	Rice code
}		
else {		
weighting_factor [0]	varies	Rice code
weighting_factor [1]	varies	Rice code
weighting_factor [2]	varies	Rice code

weighting_factor [3]	varies	Rice code
weighting_factor [4]	varies	Rice code
weighting_factor [5]	varies	Rice code
time_difference_sign	1	uimsbf
time_difference_index	5,6,7	uimsbf

Table 11.5 – Syntax of RLSLMS_extension_data

Syntax	No. of bits	Mnemonic
RLSLMS_extension()		
{		
mono_block	1	uimsbf
ext_mode	1	
if (ext_mode) {		
extension_bits	3	uimsbf
if (extension_bits&0x01) {		
RLS_order	4	uimsbf
LMS_stage	3	uimsbf
for(i=0; i<LMS_stage;i++) {		
LMS_order[i]	5	uimsbf
}		
}		
if (extension_bits&0x02) {		
if (RLS_order) {		
RLS_lambda	10	uimsbf
if (RA)		
RLS_lambda_ra	10	uimsbf
}		
if (extension_bits&04) {		
for(i=0; i<LMS_stage;i++) {		
LMS_mu[i]	5	uimsbf
}		
LMS_stepsize	3	uimsbf
}		
}		
}		

11.4.3 Payloads for Floating-Point Data

Table 11.6 – Syntax of diff_float_data

Syntax	No. of bits	Mnemonic
diff_float_data()		
{		
use_acf;	1	uimsbf
if (random_access_block) {		
if (c=0; c < channels; c++) {		
last_acf_mantissa[c] = 0;		
last_shift_value[c] = 0;		
}		

FlushDict();			
}			
for (c = 0; c < channels; c++) {			
if (use_acf == 1) {			
acf_flag[c];	1	uimsbf	
if (acf_flag[c] == 1) {	23	uimsbf	
acf_mantissa[c];			
last_acf_mantissa[c] = acf_mantissa[c];			
}			
else {			
acf_mantissa[c] = last_acf_mantissa[c];			
}			
}			
else {			
acf_mantissa[c] = last_acf_mantissa[c] = 0;			
}			
highest_byte[c];	2	uimsbf	
shift_amp[c];	1	uimsbf	
partA_flag[c];	1	uimsbf	
if (shift_amp[c] == 1) {			
shift_value[c];	8	uimsbf	
last_shift_value[c] = shift_value[c];			
}			
else {			
shift_value[c] = last_shift_value[c];			
}			
diff_mantissa();			
byte_align;	0..7	bslbf	
}			

Note: "byte_align" stands for padding of bits to the next byte boundary. "FlushDicf()" is the function that clears and initializes the dictionary and variables of the Masked-LZ decompression module (See section 11.6.9).

Table 11.7 – Syntax of diff_mantissa

Syntax	No. of bits	Mnemonic
diff_mantissa()		
{		
if (partA_flag[c] != 0) {		
compressed_flag[c];	1	uimsbf
if (compressed_flag[c] == 0) {		
for (n = 0; n < frame_length; n++) {		
if (int_zero[c][n]) {		
float_data[c][n];	32	IEEE32
}		
}		
}		
else {		
nchars = 0;		
for (n = 0; n < frame_length; n++) {		
if (int_zero[c][n])		
nchars += 4;		
}		
Masked_LZ_decompression(nchars);		
}		
if (highest_byte[c] != 0) {		
compressed_flag[c];	1	uimsbf

<pre> if (compressed_flag[c][n] == 0) { for (n = 0; n < frame_length; n++) { if (!int_zero[c][n]) { mantissa[c][n]; } } } else { nchars = 0; for (n = 0; n < frame_length; n++) { if (!int_zero[c][n]) { nchars += (int)nbits[c][n]/8; if ((nbits[c][n] % 8) > 0) nchars++; } } Masked_LZ_decompression(nchars); } } </pre>	nbits[c][n]	uimsbf
---	--------------------	---------------

Note: “int_zero” is true if the corresponding truncated integer is 0. “nbit” is the necessary word length for the difference of mantissa (see section 11.6.9).

Table 11.8 – Syntax of Masked_LZ_decompression

Syntax	No. of bits	Mnemonic
<pre> Masked_LZ_decompression(nchars) { for (dec_chars = 0; dec_chars < nchars;) { string_code; } } </pre>	9..14	uimsbf

Note: “nchars” is the number of characters need to be decoded (see section 11.6.9).

11.5 Semantics

In the following, the general elements are described. Additional elements related to floating-point audio data are described in chapter 11.5.2.

11.5.1 General Semantics

11.5.1.1 ALSSpecificConfig

ALSSpecificConfig contains general configuration data. Optionally, the header and trailer of an original audio file can be embedded in order to restore that information in addition to the actual audio data. The syntax of ALSSpecificConfig is defined in Table 11.1, its elements are described in Table 11.9.

Table 11.9 – Elements of ALSSpecificConfig

Field	#Bits	Description / Values
samp_freq	32	Sampling frequency in Hz
samples	32	Number of samples (per channel)
channels	16	Number of channels-1 (0 = mono, 1 = stereo, ...)
file_type	3	000 = unknown / raw file

		001 = wave file 010 = aiff file 011 = bwf file (other values are reserved)
resolution	3	000 = 8-bit 001 = 16-bit 010 = 24-bit 011 = 32-bit (other values are reserved)
floating	1	1 = IEEE 32-bit floating-point, 0 = integer
msb_first	1	Original byte order of the input audio data: 0 = least significant byte first (little-endian) 1 = most significant byte first (big-endian) If resolution = 0 (8-bit data), msb_first = 0 indicates unsigned data (0...255), while msb_first = 1 indicates signed data (-128..127).
frame_length	16	Frame Length - 1 (e.g. frame_length = 0x1FFF signals a frame length of N = 8192)
random_access	8	Distance between RA frames (in frames, 0...255). If no RA is used, the value is zero. If each frame is an RA frame, the value is 1.
ra_flag	2	Indicates where the size of random access units (ra_unit_size) is stored: 00: not stored 01: stored at the beginning of frame_data() 10: stored at the end of ALSSpecificConfig()
adapt_order	1	Adaptive Order: 1 = on, 0 = off
coef_table	2	Table index (00, 01, or 10, see Table 11.20) of Rice code parameters for entropy coding of predictor coefficients, 11 = no entropy coding
long_term_prediction	1	Long term prediction (LTP): 1 = on, 0 = off
max_order	10	Maximum prediction order (0..1023)
block_switching	2	Number of block switching levels: 00 = no block switching 01 = up to 3 levels 10 = 4 levels 11 = 5 levels
bgmc_mode	1	BGMC Mode: 1 = on, 0 = off (Rice coding only)
sb_part	1	Sub-block partition for entropy coding of the residual. if bgmc_mode = 0: 0 = no partition, no ec_sub bit in block_data 1 = 1:4 partition, one ec_sub bit in block_data if bgmc_mode = 1:

		0 = 1:4 partition, one ec_sub bit in block_data 1 = 1:2:4:8 partition, two ec_sub bits in block_data
joint_stereo	1	Joint Stereo: 1 = on, 0 = off If channels = 0 (mono), joint_stereo = 0
mc_coding	1	Extended inter-channel coding: 1 = on, 0 = off If channels = 0 (mono), mc_coding = 0
chan_config	1	Indicates that a chan_config_info field is present
chan_sort	1	Channel rearrangement: 1 = on, 0 = off If channels = 0 (mono), chan_sort = 0
crc_enabled	1	Indicates that the crc field is present
RLSLMS	1	Use RLS-LMS predictor: 1 = on, 0 = off
(reserved)	5	
aux_data_enabled	1	Indicates that auxiliary data is present (fields aux_size and aux_data)
chan_config_info	16	Mapping of channels to loudspeaker locations. Each bit indicates whether a channel for a particular predefined location exists (see subclause 11.6.1.5).
chan_pos[]	(channels+1)*ChBits	If channel rearrangement is on (chan_sort = 1), these are the original channel positions. The number of bits per channel is ChBits = ceil[log2(channels+1)] = 1..16 where channels+1 is the number of channels.
header_size	16	Header size of original audio file in bytes
trailer_size	16	Trailer size of original audio file in bytes
orig_header[]	header_size*8	Header of original audio file
orig_trailer[]	trailer_size*8	Trailer of original audio file
crc	32	32-bit CCITT-32 CRC checksum of the original audio data bytes (polynomial: $x^{32} + x^{26} + x^{23} + x^{22} + x^{16} + x^{12} + x^{11} + x^{10} + x^8 + x^7 + x^5 + x^4 + x^2 + x + 1$).
ra_unit_size[]	#frames*32	Distances (in bytes) between the random access frames, i.e. the sizes of the random access units, where the number of frames is #frames = ((samples-1) / (frame_length+1)) +1 In ALSSpecificConfig(), this field appears only if ra_flag = 1.
aux_size	16	Size of the aux_data field in bytes
aux_data	aux_size*8	Auxiliary data (not required for decoding)

11.5.1.2 frame_data

This is the top level payload of ALS. If random_access > 0, the number of payloads mapped into one access unit equals the value of random_access (1...255). In this case, the size of each access unit can be stored in ra_unit_size. If random_access = 0, all payloads are mapped into the same access unit.

The bs_info field holds the block switching information for a channel or a channel pair (see subclause 11.6.2 for details). The syntax of frame_data is defined in Table 11.2, its elements are described in Table 11.10.

Table 11.10 – Elements of frame_data

Field	#Bits	Description / Values
ra_unit_size	32	Distance (in bytes) to the next random access frame, i.e the size of the random access unit. In frame_data(), this field appears only if ra_flag = 2.
bs_info	8, 16, 32	Block switching information. If block_switching = 0, no bs_info field is transmitted, otherwise #Bits depends on the value of block_switching: block_switching = 1: 8 bits block_switching = 2: 16 bits block_switching = 3: 32 bits
js_switch	1	If js_switch = 1, Joint Stereo (channel difference) is selected even if MCC (mc_coding) is enabled.
num_bytes_diff_float	32	Only present if floating = 1: Number of bytes for diff_float_data

11.5.1.3 block_data

The block data specifies the type of block (normal, constant, silence) and basically contains the code indices, the predictor order, the predictor coefficients and the coded residual values. The syntax of block_data is defined in Table 11.3, its elements are described in Table 11.11.

Table 11.11 – Elements of block_data

Field	#Bits	Description / Values
block_type	1	1 = normal block 0 = zero / constant block
const_block	1	Only if block_type = 0: 1 = constant block 0 = zero block (silence)
js_block	1	Block contains a joint stereo difference signal
const_val	8,16,24,32	Constant sample value of this block
ec_sub	0..2	Number of sub-blocks for entropy coding. #Bits = bgmc_mode + sb_part if #Bits = 0: 1 sub-block if #Bits = 1: 0 = 1 sub-block 1 = 4 sub-blocks if #Bits = 2 00 = 1 sub-block 01 = 2 sub-blocks 10 = 4 sub-blocks 11 = 8 sub-blocks

s[],sx[]	varies	Up to 8 Rice (s) or BGMC (s,sx) code indices for entropy coding of sub-blocks (number is given by ec_sub). The differential values are Rice coded.
shift_lsbs	1	Indicates that all original input sample values of this block have been shifted to the right prior to further processing, in order to remove empty LSBs
shift_pos	4	Number of positions-1 that the sample values of this block have been shifted to the right: 0000 = 1 position ... 1111 = 16 positions
opt_order	1..10	Predictor order for this block (of length N_B). $\#Bits = \min\{\lceil\log_2(\max_order+1)\rceil, \max\{\lceil\log_2((N_B >> 3)-1)\rceil, 1\}\}$ The number of bits is restricted by both the maximum order (max_order) and the block length N_B (see subclause 11.6.3.1)
quant_cof[]	varies	Rice coded quantized coefficients. The Rice coding scheme is described in subclause 11.6.6.1
LTPenable	1	LTP switch, 1 = on, 0 = off
LTPgain[]	varies	Rice coded gain values (5-tap)
LTPlag	8,9,10	LTP lag values Freq < 96000, range=0..255, bit=8 96000 <= Freq < 192000, range=0..511, bit=9 Freq >= 192000 range=0..1023, bit=10
smp_val[0]	varies	Rice coded sample value at the beginning of a random access block (see Table 11.22)
res[]	varies	Rice coded residual values (see subclause 11.6.6.1)
msb[]	varies	BGMC-coded most significant bits of residuals. For residuals outside the central region, the special "tail_code" is transmitted. The BGMC coding scheme is described in subclause 11.6.6.2
lsb[]	varies	Directly transmitted least significant bits of the residuals (see subclause 11.6.6.2)
tail[]	varies	Rice coded residual values outside the central region (tails, see subclause 11.6.6.2)

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11.5.1.4 channel_data

The syntax of channel_data is defined in Table 11.4, its elements are described in Table 11.12.

Table 11.12 – Elements of channel_data

Field	#Bits	Description / Values
stop_flag	1	0: Continue description of inter-channel relationship 1: Stop description
master_channel_index	1..16	Index of master-channel. #Bits = ceil[log2(channels+1)] where channels+1 is the number of channels
time_difference_flag	1	0: 3-tap without time difference lag 1: 6-tap with time difference lag
weighting factor	varies	Indices of inter-channel weighting factor
time_difference_sign	1	0: positive, 1:negative; “Positive” means that the reference channel is delayed relative to the coding channel.
time_difference_value	5,6,7	Absolute value of time difference lag Freq < 96000, range=3..34, #Bits=5 96000 <= Freq < 192000, range=3..66, #Bits=6 Freq >= 192000 range=3..130, #Bits=7

11.5.1.5 RLSLMS_extension_data

The syntax of RLSLMS_extension_data is defined in Table 11.5, its elements are described in Table 11.13.

Table 11.13 – Elements of RLSLMS_extension_data

Field	#Bits	Description / Values
mono_block	1	mono_frame == 0: CPE coded with joint-stereo RLS mono_frame == 1: CPE coded with mono RLS
ext_mode	1	RLS-LMS predictor parameters are updated in extension block. 1 == extension block 0 == non-extension block
extension_bits	3	Type of RLS-LMS parameters carried in extension block xtension&01 == RLS-LMS predictors orders extension&02 == RLS_lambda and RLS_lambda_ra extension&04 == LMS_mu and LMS_stepsize
RLS_order	4	RLS predictor order

LMS_stage	3	Number of LMS predictors in cascade
LMS_order[]	5*LMS_stage	LMS predictor order
RLS_lambda	10	RLS predictor parameter lambda.
RLS_lambda_ra	10	RLS predictor parameter lambda for random access frame
LMS_mu[]	5*LMS_stage	LMS predictor parameter mu
LMS_stepsize	3	LMS predictor parameter stepsize

11.5.2 Semantics for Floating-Point Data

11.5.2.1 diff_float_data

The syntax of diff_float_data is defined in Table 11.6, its elements are described in Table 11.14.

Table 11.14 – Elements of diff_float_data

Field	#Bits	Description / Values
use_acf	1	1: acf_flag[c] is present 0: acf_flag[c] is not present
acf_flag[c]	1	1: acf_mantissa[c] is present 0: acf_mantissa[c] is not present
acf_mantissa[c]	23	Full mantissa data of common multiplier
highest_byte[c]	2	Highest nonzero bytes of mantissa in a frame
partA_flag[c]	1	1: Samples exist in Part-A 0: No sample exists or all zero in Part-A
shift_amp[c]	1	1: shift_value[c] is present 0: shift_value[c] is not present
shift_value[c]	8	Shift value: This value is added to the exponent of all floating-point values of channel c after conversion of decoded integer to floating-point values, and before addition of integer and the difference data.

11.5.2.2 diff_mantissa

The syntax of diff_mantissa is defined in Table 11.7, its elements are described in Table 11.15.

Table 11.15 – Elements of diff_mantissa

Field	#Bits	Description / Values
int_zero[c][n]	(varies)	int_zero for n-th sample and c-th channel is set if the truncated integer equals "0". This value is not a syntactic element, but can be determined from the associated integer value which is available in both the encoder and the decoder.
mantissa[c][n]	nbits[c][n]	Full mantissa data

compresed_flag[c]	1	1: Samples are compressed 2: Samples are uncompressed
nchars	(varies)	Number of characters to be decoded
float_data[c][n]	32	32-bit IEEE floating-point value
nbits[c][n]		This value is not a syntactic element. This can be determined from the integer value, acf_mantissa[c] and highest_byte[c].

11.5.2.3 Masked_LZ_decompression

The syntax of Masked_LZ_decompression is defined in Table 11.8, its elements are described in Table 11.16.

Table 11.16 – Elements of Masked_LZ_decompression

Field	#Bits	Description / Values
string_code	code_bits	Index code of the dictionary.
code_bits	(varies)	code_bits is varied from 9 to 15 bits depending on the number of entries stored in the dictionary

11.6 ALS Tools

In most *lossy* MPEG coding standards, only the *decoder* is specified in detail. However, a *lossless* coding scheme usually requires the specification of some (but not all) *encoder* portions. Since the encoding process has to be perfectly reversible without loss of information, several parts of both encoder *and* decoder have to be specified in a deterministic way.

Block diagrams of the lossless encoder and the lossless decoder were already shown in Figure 11.1. In the rest of this section, the decoding process will be described along with those elements of the encoder which must be specified exactly in order to ensure lossless decoding.

11.6.1 Overview

11.6.1.1 Bitstream structure

An example for the general bitstream structure of a compressed *M*-channel file is shown in Figure 11.2.

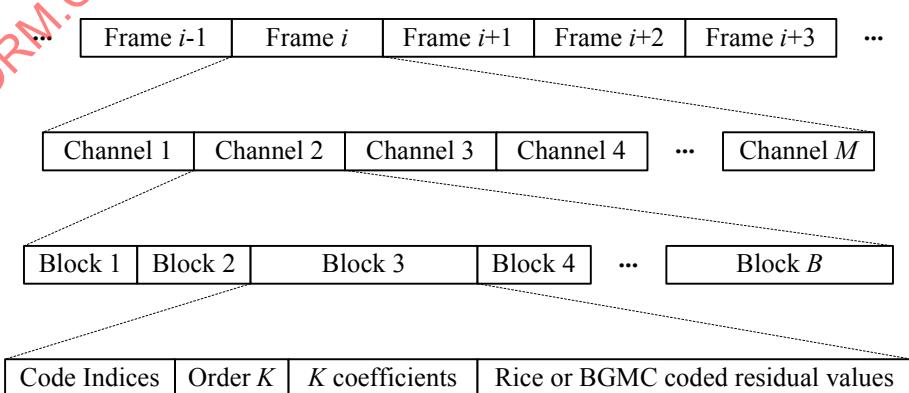


Figure 11.2 – General bitstream structure of a compressed audio file

Each frame (frame_data) consists of $B = 1 \dots 32$ sample blocks (block_data) for each channel. Besides general information about the block (e.g. silence block, joint stereo difference block, etc.), each block typically contains the code indices, the predictor order K , the predictor coefficients and the Rice- or BGMC-coded residual values. Variations of this slightly simplified structure are treated in detail in the following sections. If joint coding between channel pairs is used, the block partition is identical for both channels, and blocks are stored in an interleaved fashion (see subclause 11.6.2, Figure 11.5). Otherwise, the block partition for each channel is independent.

If the input is floating-point data, additional bitstream elements for differential mantissa values are inserted after the bitstream of every integer frame. Please refer to subclause 11.6.9 for a detailed description of the floating-point extensions.

11.6.1.2 Decoding of ALSSpecificConfig

ALSSpecificConfig contains information about the original data (e.g. "samp_freq", "channels", "resolution") as well as global parameters that do not change from frame to frame (e.g. "frame_length", "max_order"). The most important parameters (some of which are optional) are briefly described in the following:

- Sampling frequency: The sampling frequency of the original audio data is stored, e.g. for direct playback of a compressed file.
- Samples: Total number of audio samples per channel.
- Number of channels: 1 (mono), 2 (stereo), or more (multichannel).
- Resolution: 8-bit, 16-bit, 24-bit, or 32-bit. If the resolution of the original audio data is somewhere in between (e.g. 20-bit), the higher resolution is used for the sample representation.
- Floating-point: Indicates the format of audio data. If this flag is set, the audio data is in the IEEE 32-bit floating-point format, otherwise the audio data is integer.
- Byte order: Indicates the byte order of the original audio file, either most significant byte first (e.g. aiff) or least significant byte first (e.g. wave).
- Frame length: Number of samples in each frame (per channel).
- Random access: Distance (in frames) between those frames which can be decoded independently from previous frames (random access frames). In front of each random access frame, there is the field "ra_unit_size" which specifies this distance in bytes.
- Adaptive order: Each block might have an individual predictor order.
- Coefficient table: A Table containing parameters that are used for entropy coding of predictor coefficients.
- Long-term-prediction: Long term prediction (LTP).
- Maximum order: Maximum order of the prediction filter. If "adapt_order" is turned off, this order is used for all blocks.
- Block Switching: Instead of one block per channel there might up to 32 shorter blocks. If block switching is not used, the block length is identical with the frame length.
- BGMC mode: Indicates the use of BGMC codes for the prediction residual. If this flag is set to 0, the simpler Rice codes are used for the prediction residual.
- Sub-block partition: Sub-block partition for entropy coding of the residual.

- Joint stereo: In each block, a difference signal might be encoded instead of the left or the right channel (or one of the two channels of a channel pair, accordingly)
- Multi-channel coding: Extended inter-channel coding
- Channel sort: Channel rearrangement, used for building dedicated channel pairs.
- Channel positions: Original channel positions, used only if `channel_sort` is turned on.
- Header size: Size of the original audio file header, in bytes.
- Trailer size: Size of trailing non-audio information in the original audio file, in bytes.
- Original header: The embedded header of the original audio file.
- Original trailer: The embedded trailer of the original audio file.
- CRC: Cyclic redundancy checksum (CCITT-32) of the original audio data bytes (i.e. in their original order, including channel interleaving).

11.6.1.3 Number of Frames

The number of frames to decode depends on the actual frame length ($N = \text{frame_length} + 1$) and the number of samples. It can be determined as follows:

```

N = frame_length + 1;
frames = samples / N;
remainder = samples % N;
if (rest)
{
    frames++;
    N_last = remainder;
}
else
    N_last = N;

```

If the number of samples is not a multiple of the frame length N , the length of the last frame is accordingly reduced ($N_{\text{last}} = \text{remainder}$).

11.6.1.4 Joint Channel Coding

In order to exploit redundancy between channels, the encoder can use a simple approach, consisting of channel pairs and single channels. The two channels of a channel pair can be encoded using difference coding (see section 11.6.7), whereas single channels are encoded independently.

The general use of joint coding is signalled by the `joint_stereo` flag in the ALS header. If `joint_stereo` is off, each channel is a single channel, and is therefore coded independently from other channels. If `joint_stereo` is on, in each case two successive channels are regarded as a channel pair. If the number of channels is odd, there is one remaining single channel.

Defining channel pairs does not mean that joint coding has to be essentially used. If `joint_stereo` is set, the decoder will treat combinations of two channels as channel pairs, even if the encoder did never actually use joint coding (e.g. since the channels were not correlated). In this case, the decoder will simply never discover a set `js_block` flag `block_data`.

11.6.1.5 Channel Configuration and Rearrangement

The chan_config_info field (if present) defines a channel-to-speaker mapping by indicating whether a channel for a particular predefined location exists. Therefore, the existing channels have to be arranged in a predefined order (see Table 11.17). If a particular channel is present, the corresponding bit in the chan_config_info field is set.

Table 11.17 – Channel Configuration

Speaker location	Abbreviation	Bit position in chan_config_info
Left	L	1
Right	R	2
Left Rear	Lr	3
Right Rear	Rr	4
Left Side	Ls	5
Right Side	Rs	6
Center	C	7
Center Rear / Surround	S	8
Low Frequency Effects	LFE	9
Left Downmix	L0	10
Right Downmix	R0	11
Mono Downmix	M	12
(reserved)		13-16

If the channels are arranged differently, channel rearrangement can be used. For 5.1 surround material with channel configuration L, R, Lr, Rr, C, LFE, it is obvious that the first two channel pairs (L/R, Lr/Rr) might benefit from joint coding, whereas the remaining channels (C, LFE) are more likely to be independent. Even so, if joint_coding is on, the encoder forms channel pairs simply by successively combining adjacent channels, thus there are three channel pairs in this case.

However, if the channel configuration is L, R, C, Lr, Rr, LFE, or L, Lr, C, Rr, R, LFE, the correlated channels are no longer adjoining. This problem can be addressed by a virtual rearrangement of channels prior to encoding, where correlated channels are grouped and successively arranged, such that they form channel pairs. The information about this rearrangement is stored in the compressed file as the original channel number in the field chan_pos[]. The decision on which channels are grouped can be made automatically by the encoder or manually by the user. If the channel configuration is indicated in the original file, the encoder can make a suitable rearrangement. If the file format has no default channel configuration, but the user knows the channel to speaker mapping in that particular case, he can instruct the encoder how to group the channels.

The decoder has to reverse a possible channel rearrangement (chan_sort flag), by assigning each channel its original position as stored in chan_pos[].

11.6.1.6 Decoding of Frames

A frame constitutes the top level payload (frame_data), i.e. the basic unit of audio data (see Table 11.2 for syntax and Table 11.10 for semantics). If block switching is used, each channel of a frame can be subdivided into up to 32 blocks. Otherwise, a block consists of all samples of a frame's channel.

11.6.1.7 Decoding of Blocks

The block_data() structure contains the information about a single block (i.e. a segment of audio data from one channel). It specifies whether the block is a “normal” block (i.e. containing encoded audio samples), a constant block (all audio samples are the same) or a silence block (all audio samples are zero). Furthermore, the field “joint_stereo” indicates whether the block contains a difference signal (right minus left channel). Either the left or the right channel can be substituted by that difference signal. This also holds in the case of block switching, when the block length may be shorter than the frame length.

For “normal” blocks, as shown in Figure 11.2, the block data basically comprises

- the code indices,
- the predictor order K ,
- the quantized and encoded predictor coefficients (or the RLS-LMS predictor parameters in the case of RLSLMS mode)
- the LTP parameters in case of LTP mode,
- and the Rice- or BGMC-coded residual values.

If the block is further subdivided into sub-blocks for entropy coding (indicated by ec_sub), code parameters s and sx are transmitted for each sub-block (see section 11.6.6 for further explanations).

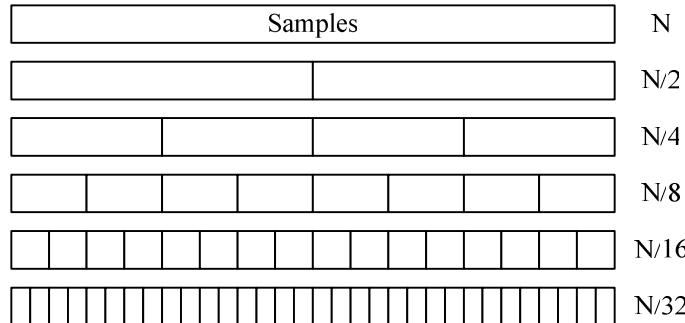
In case of an adaptive predictor order (adapt_order), the order for the block is indicated (opt_order). There is also a flag (shift_lsbs) specifying whether all audio samples in the current block have some LSBs which are persistently zero. If this is the case, the number of empty LSBs is given in another field (shift_pos). This means that the encoder has shifted all sample values to the right by shift_pos+1 positions prior to prediction. Thus, the decoder has to shift the output sample values to the left by shift_pos+1 positions after the inverse prediction filter has been applied. If the prediction process uses samples from a previous block, a shifted version of these samples has to be used as input of both the prediction filter and the inverse prediction filter (i.e. in both the encoder and the decoder), even if the LSBs are not zero in the previous block. This is necessary in order to align the amplitude range of the predictor's input samples with the samples to be predicted.

11.6.1.8 Interleaving

Most uncompressed audio file formats store the two channels of a stereo signal as a sequence of interleaved samples ($L_1, R_1, L_2, R_2, L_3, R_3, \dots$). For multichannel data with M channels, each sample step comprises M interleaved samples, e.g. $L_1, R_1, Lr_1, Rr_1, C_1, LFE_1, L_2, \dots$ in the case of 5.1 material. Since the encoder builds blocks of samples for each channel, the decoded samples of all channels may have to be interleaved again before writing them to an output audio file.

11.6.2 Block Switching

If block_switching is enabled, each channel of a frame can be hierarchically subdivided into up to 32 blocks (see Figure 11.3).

**Figure 11.3 – Block switching hierarchy**

Arbitrary combinations of blocks with $N_B = N$, $N/2$, $N/4$, $N/8$, $N/16$, and $N/32$ are possible within a frame, as long as each block results from a subdivision of a superordinate block of double length. Therefore, a partition into $N/4 + N/4 + N/2$ is possible, whereas a partition into $N/4 + N/2 + N/4$ is not (Figure 11.4).

N			(0)000 0000		
N/2	N/4	N/4	(0)101 0000		
N/4	N/4	N/2	(0)110 0000		
N/4	N/8	N/8	N/4	(0)111 0100	
N/4	N/2		N/4	not possible	
N/8	N/4	N/8	N/4	N/4	not possible

Figure 11.4 – Block switching examples and corresponding bs_info codes

The actual partition is signalled in an additional field *bs_info* (right column in Figure 11.4), whose length depends on the number of block switching levels (see Table 11.18).

Table 11.18 – Block switching levels

Maximum #levels	Minimum N_B	#Bytes for <i>bs_info</i>
0	N	0
1	N/2	1
2	N/4	1
3	N/8	1
4	N/16	2
5	N/32	4

The *bs_info* field consists of up to 4 bytes, where the mapping of bits with respect to the levels 1 to 5 is [(0)1223333 44444444 55555555 55555555]. The first bit is only used to signal independent block switching (independent_bs, see Table 11.2). In the example of Figure 11.4, there are three levels, thus the minimum block length is $N_B = N/8$, and *bs_info* consists of one byte. Starting at the maximum block length $N_B = N$, the bits of *bs_info* are set if a block is further subdivided. For the topmost example there is no subdivision at all, thus the code is (0)0000000. The frame in the second row is subdivided ((0)1...), where only the second block of length $N/2$ is further split ((0)101...) into two blocks of length $N/4$. If an $N/4$ block is split as in the fourth row, it is indicated in the following bits ((0)111 0100).

In each frame, `bs_info` fields are transmitted for all channel pairs and all single channels respectively, enabling independent block switching for different channels. While the frame length is identical for all channels, block switching can be done individually for each channel. If difference coding is used, both channels of a channel pair have to be switched synchronously, but other channel pairs can still use different block switching.

However, if the two channels of a channel pair are not correlated with each other, difference coding will not pay off, and thus there will be no need to switch both channels synchronously. Instead, it may rather make sense to switch the channels independently.

Typically, there will be a `bs_info` field for each channel pair and single channel in a frame, i.e. the two channels of a channel pair are switched synchronously. If they are switched independently, the first bit of `bs_info` is set to 1, and the information applies to the channel pair's first channel. In this case, another `bs_info` field for the second channel becomes necessary.

An example for a three-channel file is shown in Figure 11.5. Short blocks are only interleaved if they belong to a channel pair that uses difference coding and therefore synchronized block switching (Figure 11.5, middle). This interleaving is necessary since in a channel pair a block of one channel (e.g. block 1.2) may depend on previous blocks from *both* channels (e.g. blocks 1.1 and 2.1), so these previous blocks have to be available prior to the current one. For channels whose blocks are switched independently, channel data is arranged separately (Figure 11.5, bottom).

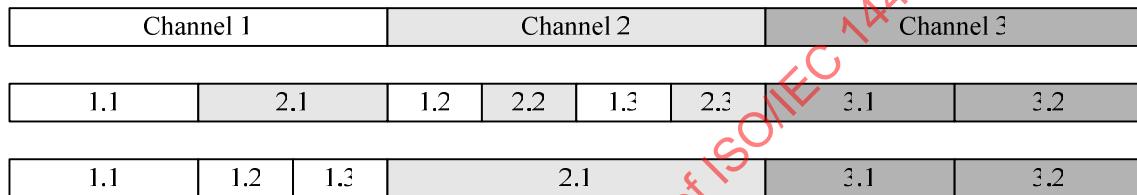


Figure 11.5 – Frame Structure: No block switching (top), synchronized block switching between channels 1 and 2 (middle), independent block switching (bottom)

If `joint_stereo` is off, all channels are switched independently without explicit signalling. If `joint_stereo` is on, but `block_switching` is off, there is only one block per channel, thus interleaving is not required (Figure 11.5, top).

11.6.3 Prediction

This chapter describes the forward-adaptive prediction scheme. Block diagrams of the corresponding encoder and decoder parts are shown in Figure 11.6 and Figure 11.7.

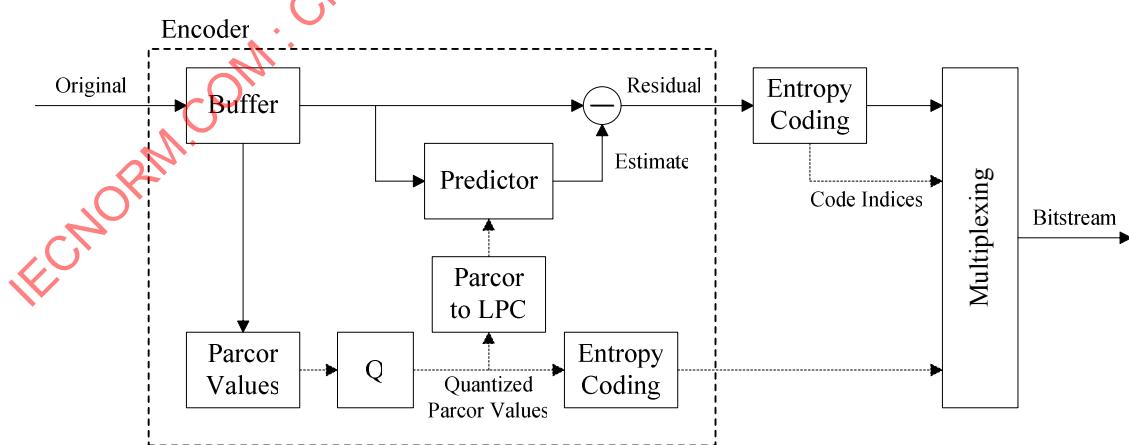


Figure 11.6 – Encoder of the forward-adaptive prediction scheme

The encoder consists of several building blocks. A buffer stores one block of input samples, and an appropriate set of parcor coefficients is calculated for each block. The number of coefficients, i.e. the order of

the predictor, can be adapted as well. The quantized parcor values are entropy coded for transmission, and converted to LPC coefficients for the prediction filter which calculates the prediction residual. The final entropy coding of the residual is described in subclause 11.6.6.

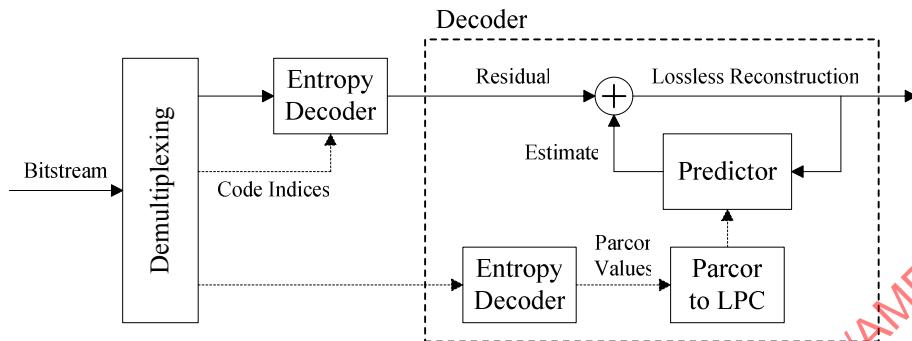


Figure 11.7 – Decoder of the forward-adaptive prediction scheme

The decoder is significantly less complex than the encoder, since no adaptation has to be carried out. The transmitted parcor values are decoded, converted to LPC coefficients, and are used by the inverse prediction filter to calculate the lossless reconstruction signal. The computational effort of the decoder mainly depends on the predictor orders chosen by the encoder. Since the average order is typically well below the maximum order, prediction with greater maximum orders does not necessarily lead to a significant increase of decoder complexity.

If the prediction order K is adaptively chosen (`adapt_order = 1`), the number of bits used for signaling the actual order (`opt_order = K`) in each block is restricted, depending on both the global maximum order (`max_order`) and the block length N_B :

$$\text{Bits} = \min\{\text{ceil}[\log_2(\text{max_order}+1)], \text{max}[\text{ceil}(\log_2((N_B>>3)-1)), 1]\}$$

Therefore, also the maximum order $K_{\text{max}} = 2^{\text{Bits}} - 1$ is restricted, depending on both the value of `max_order` and the block length (see Table 11.19).

Table 11.19 – Maximum prediction order depending on block length and max_order

N_B	$\text{max_order} = 1023$		$\text{max_order} = 100$	
	#Bits for <code>opt_order</code>	K_{max}	#Bits for <code>opt_order</code>	K_{max}
> 4096	10	1023	7	100
> 2048	9	511	7	100
> 1024	8	255	7	100
> 512	7	127	7	100
> 256	6	63	6	63
> 128	5	31	5	31
> 64	4	15	4	15
> 32	3	7	3	7
> 16	2	3	2	3
> 8	1	1	1	1

The basic (short-term) prediction can be combined with long-term prediction (LTP, see subclause 11.6.4). An alternative prediction scheme based on backward-adaptive predictors is described in subclause 11.6.5.

11.6.3.1 Predictor Coefficients

The transmission of the prediction filter coefficients is accomplished by using *parcor coefficients* γ_k , $k = 1 \dots K$ (where K is the order of the filter), which can be obtained e.g. by using the Levinson-Durbin algorithm.

11.6.3.1.1 Quantization and encoding of parcor coefficients

The first two parcor coefficients (γ_1 and γ_2 correspondingly) are quantized by using the following companding functions:

$$a_1 = \left\lfloor 64 \left(-1 + \sqrt{2} \sqrt{\gamma_1 + 1} \right) \right\rfloor; \\ a_2 = \left\lfloor 64 \left(-1 + \sqrt{2} \sqrt{-\gamma_2 + 1} \right) \right\rfloor;$$

while the remaining coefficients are quantized using simple 7-bit uniform quantizers:

$$a_k = \left\lfloor 64 \gamma_k \right\rfloor; \quad (k > 2).$$

In all cases the resulting quantized values a_k are restricted to the range [-64, 63].

Transmission of the quantized coefficients a_k is done by producing residual values

$$\delta_k = a_k - \text{offset}_k,$$

which, in turn, are encoded by using Rice codes as described in section 11.6.6.1. The corresponding offsets and parameters of Rice codes used in this process can be globally chosen from one of the sets in Table 11.20, where the table index (coef_table) is indicated in ALSSpecificConfig. If coef_table = 11, then no entropy coding is applied, and the quantized coefficients are transmitted with 7 bits each. In this case, the offset is always -64 in order to obtain unsigned values $\delta_k = a_k + 64$ that are restricted to [0, 127].

Table 11.20 – Rice code parameters used for encoding of parcor coefficients

	coef_table = 00		coef_table = 01		coef_table = 10	
Coefficient #	Offset	Rice parameter	Offset	Rice parameter	Offset	Rice parameter
1	-52	4	-58	3	-59	3
2	-29	5	-42	4	-45	5
3	-31	4	-46	4	-50	4
4	19	4	37	5	38	4
5	-16	4	-36	4	-39	4
6	12	3	29	4	32	4
7	-7	3	-29	4	-30	4
8	9	3	25	4	25	3
9	-5	3	-23	4	-23	3
10	6	3	20	4	20	3
11	-4	3	-17	4	-20	3
12	3	3	16	4	16	3
13	-3	2	-12	4	-13	3

14	3	2	12	3	10	3
15	-2	2	-10	4	-7	3
16	3	2	7	3	3	3
17	-1	2	-4	4	0	3
18	2	2	3	3	-1	3
19	-1	2	-1	3	2	3
20	2	2	1	3	-1	2
$2k-1, 10 < k < 65$	0	2	0	2	0	2
$2k, 10 < k < 64$	1	2	1	2	1	2
$k > 127$	0	1	0	1	0	1

11.6.3.1.2 Reconstruction of the parcor coefficients

First, Rice-decoded residual values δ_k are combined with offsets (see Table 11.20) to produce quantized indices of parcor coefficients a_k :

$$a_k = \delta_k + \text{offset}_k.$$

Then, the reconstruction of the first two coefficients is done using:

$$\text{par}_1 = \lfloor \hat{\gamma}_1 2^Q \rfloor = \Gamma(a_1);$$

$$\text{par}_2 = \lfloor \hat{\gamma}_2 2^Q \rfloor = -\Gamma(a_2);$$

where 2^Q represents a constant ($Q=20$) scale factor required for integer representation of the reconstructed coefficients, and $\Gamma(\cdot)$ is a mapping described in the following table.

Table 11.21 – Indices i and corresponding scaled parcor values $\Gamma(i)$ for $i = -64 \dots 63$

i	$\Gamma(i)$	i	$\Gamma(i)$	i	$\Gamma(i)$	i	$\Gamma(i)$
-64	-1048544	-32	-913376	0	-516064	32	143392
-63	-1048288	-31	-904928	1	-499424	33	168224
-62	-1047776	-30	-896224	2	-482528	34	193312
-61	-1047008	-29	-887264	3	-465376	35	218656
-60	-1045984	-28	-878048	4	-447968	36	244256
-59	-1044704	-27	-868576	5	-430304	37	270112
-58	-1043168	-26	-858848	6	-412384	38	296224
-57	-1041376	-25	-848864	7	-394208	39	322592
-56	-1039328	-24	-838624	8	-375776	40	349216
-55	-1037024	-23	-828128	9	-357088	41	376096
-54	-1034464	-22	-817376	10	-338144	42	403232
-53	-1031648	-21	-806368	11	-318944	43	430624
-52	-1028576	-20	-795104	12	-299488	44	458272

-51	-1025248	-19	-783584	13	-279776	45	486176
-50	-1021664	-18	-771808	14	-259808	46	514336
-49	-1017824	-17	-759776	15	-239584	47	542752
-48	-1013728	-16	-747488	16	-219104	48	571424
-47	-1009376	-15	-734944	17	-198368	49	600352
-46	-1004768	-14	-722144	18	-177376	50	629536
-45	-999904	-13	-709088	19	-156128	51	658976
-44	-994784	-12	-695776	20	-134624	52	688672
-43	-989408	-11	-682208	21	-112864	53	718624
-42	-983776	-10	-668384	22	-90848	54	748832
-41	-977888	-9	-654304	23	-68576	55	779296
-40	-971744	-8	-639968	24	-46048	56	810016
-39	-965344	-7	-625376	25	-23264	57	840992
-38	-958688	-6	-610528	26	-224	58	872224
-37	-951776	-5	-595424	27	23072	59	903712
-36	-944608	-4	-580064	28	46624	60	935456
-35	-937184	-3	-564448	29	70432	61	967456
-34	-929504	-2	-548576	30	94496	62	999712
-33	-921568	-1	-532448	31	118816	63	1032224

Reconstruction of the 3rd and higher order coefficients is done using the formula

$$\text{par}_k = \lfloor \hat{\gamma}_k 2^Q \rfloor = a_k 2^{Q-6} + 2^{Q-7}; \quad (k > 2).$$

11.6.3.1.3 Conversion of reconstructed parcor coefficients into direct filter coefficients

The scaled parcor coefficients are then converted to LPC coefficients using the following algorithm:

```

short m, i, K, Q = 20;
long *cof, *par, corr = 1 << (Q - 1);
INT64 temp, temp2;
for (m = 1; m <= K; m++)
{
    for (i = 1; i <= m/2; i++)
    {
        temp = cof[i] + (((INT64)par[m] * cof[m-i]) + corr) >> Q;
        if ((temp > LONG_MAX) || (temp < LONG_MIN)) // Overflow: use different coefficients
            return(1);
        temp2 = cof[m-i] + (((INT64)par[m] * cof[i]) + corr) >> Q;
        if ((temp2 > LONG_MAX) || (temp2 < LONG_MIN)) // Overflow: use different coefficients
            return(1);
        cof[m-i] = (long)temp2;
        cof[i] = (long)temp;
    }
    cof[m] = par[m];
}

```

Here, $\text{LONG_MAX} = 2^{31} - 1$ and $\text{LONG_MIN} = -(2^{31})$. The resulting LPC coefficients cof are scaled by 2^{20} as well. The scaling will be accounted for during the filtering process.

11.6.3.2 Prediction Filter

The calculation of the predicted signal has to be done in a deterministic way to enable identical calculation in both the encoder and the decoder, hence we cannot use floating point coefficients. Instead we employ an upscaled integer representation as shown in the last section. Since the coefficients are enlarged by a factor $2^Q = 2^{20}$, also the predicted signal will be enlarged by the same factor. Thus, at the end of the filtering process, each sample of the predicted signal has to be scaled down.

11.6.3.2.1 Encoder

The following algorithm describes the calculation of the residual d for an input signal x , a predictor order K and LPC coefficients cof .

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```

short n, N, k, K, Q = 20;
long *x, *d, *cof, corr = 1 << (Q - 1);
INT64 y;
for (n = 0; n < N; n++)
{
    y = corr;
    for (k = 1; k <= K; k++)
        y += (INT64)cof[k-1] * x[n-k];
    d[n] = x[n] + (long)(y >> Q);
}

```

As can be seen from the code, the predictor uses the last K samples from the previous block to predict the first sample of the current block.

If the current block (or sub-block) is a channel's first block in a random access frame, no samples from the previous block may be used. In this case, prediction with progressive order is employed, where the scaled parcor coefficients par are converted progressively to LPC coefficients cof inside the prediction filter. In each recursion, the current residual value $d(n)$ and a new set of $n+1$ LPC coefficients is calculated (first loop). After the first K residual values and all K coefficients are calculated, full-order prediction is used (second loop). Please note that the indices for par and cof start with 1 in this implementation.

```

short m, n, N, i, k, K, Q = 20;
long *x, *d, *cof, corr = 1 << (Q - 1);
INT64 y, temp, temp2;
for (n = 0; n < K; n++)
{
    y = corr;
    for (k = 1; k <= n; k++)
        y += (INT64)cof[k] * x[n-k];
    d[n] = x[n] + (long)(y >> Q);
    m = n + 1;
    for (i = 1; i <= m/2; i++)
    {
        temp = cof[i] + (((INT64)par[m] * cof[m-i]) + corr) >> Q;
        if ((temp > LONG_MAX) || (temp < LONG_MIN)) // Overflow: use different coefficients
            return(1);
        temp2 = cof[m-i] + (((INT64)par[m] * cof[i]) + corr) >> Q;
        if ((temp2 > LONG_MAX) || (temp2 < LONG_MIN)) // Overflow: use different coefficients
            return(1);
        cof[m-i] = (long)temp2;
        cof[i] = (long)temp;
    }
    cof[m] = par[m];
}
for (n = K; n < N; n++)
{
    y = corr;
    for (k = 1; k <= K; k++)
        y += (INT64)cof[k] * x[n-k];
    d[n] = x[n] + (long)(y >> Q);
}

```

Only the first sample $x(0)$ is transmitted directly, using a Rice code with $s = resolution - 4$ (i.e. $s = 12$ for 16-bit and $s = 20$ for 24-bit). The following two residual values $d(1)$ and $d(2)$ are coded with Rice codes which are related to the block's first Rice parameter $s[0]$ (see section 11.6.1.7). Depending on the entropy coder, the remaining residual values $d(3)$ to $d(K)$ are either Rice coded with $s[0]$ or BGMC coded with $s[0]$ and $sx[0]$. A summary of all codes is given in Table 11.22.

Table 11.22 – Code parameters for different sample positions

Sample / Residual	Code Parameter
$x(0)$	resolution – 4
$d(1)$	$s[0] + 3$
$d(2)$	$s[0] + 1$
$d(3) \dots d(K)$	$s[0]$ (BGMC: $sx[0]$)

11.6.3.2.2 Decoder

The algorithm for the calculation of the original signal in the decoder is nearly identical with the encoder's algorithm, except for the last instruction:

```
short n, N, k, K, Q = 20;
long *x, *d, corr = 1 << (Q - 1);
INT64 y;
for (n = 0; n < N; n++)
{
    y = corr;
    for (k = 1; k <= K; k++)
        y += (INT64)cof[k-1] * x[n-k];
    x[n] = d[n] - (long)(y >> Q);
}
```

In the case of random access, prediction with progressive order is used. The algorithm for the calculation is also nearly identical with the encoder's algorithm, except for the two lines where x is calculated. Again, the indices for par and cof start with 1.

```
short m, n, N, i, k, K, Q = 20;
long *x, *d, *cof, corr = 1 << (Q - 1);
INT64 y, temp, temp2;
for (n = 0; n < K; n++)
{
    y = corr;
    for (k = 1; k <= n; k++)
        y += (INT64)cof[k] * x[n-k];
    x[n] = d[n] - (long)(y >> Q);
    m = n + 1;
    for (i = 1; i <= m/2; i++)
    {
        temp = cof[i] + (((INT64)par[m] * cof[m-i]) + corr) >> Q;
        temp2 = cof[m-i] + (((INT64)par[m] * cof[i]) + corr) >> Q;
        cof[m-i] = (long)temp2;
        cof[i] = (long)temp;
    }
    cof[m] = par[m];
}
for (n = K; n < N; n++)
{
    y = corr;
    for (k = 1; k <= K; k++)
        y += (INT64)cof[k] * x[n-k];
    x[n] = d[n] - (long)(y >> Q);
}
```

If joint channel coding has been used by the encoder, the decoded signal x might be a difference signal. In this case further processing has to be done to obtain the original signal (see next section).

11.6.4 Long-term prediction (LTP)

11.6.4.1 LTP gain and lag

If LTPenable is on, 5-tap gain values $\rho(i)$ and a lag value τ are decoded. The gain values $\rho(i)$ are reconstructed from the Rice coded indices listed in Table 11.23, Table 11.24, and Table 11.25.

Table 11.23 – Reconstruction values and the Rice code for gain of $\rho(0)$

gain values $\rho(0) * 128$	index	prefix	sub-code
0	0	0	00
8	1	0	01
16	2	0	10
24	3	0	11
32	4	10	00
40	5	10	01
48	6	10	10
56	7	10	11
64	8	110	00
70	9	110	01
76	10	110	10
82	11	110	11
88	12	1110	00
92	13	1110	01
96	14	1110	10
100	15	1110	11

Table 11.24 – Reconstruction values and the Rice code for gain of $\rho(\pm 1)$

gain values $\rho(\pm 1) * 128$	index	prefix	sub-code
0	0	0	00
-8	1	0	01
8	2	0	10
-16	3	0	11
16	4	10	00
-24	5	10	01
24	6	10	10
-32	7	10	11

32	8	110	00
-40	9	110	01
40	10	110	10
-48	11	110	11
48	12	1110	00
-56	13	1110	01
56	14	1110	10
-64	15	1110	11

Table 11.25 – Reconstruction values and the Rice code for gain of $\rho(\pm 2)$

gain values $\rho(\pm 2)^{*}128$	index	prefix	sub-code
0	0	0	0
-8	1	0	1
8	2	10	0
-16	3	10	1
16	4	110	0
-24	5	110	1
24	6	1110	0
-32	7	1110	1
32	8	11110	0
-40	9	11110	1
40	10	111110	0
-48	11	111110	1

The transmitted relative lag value is the actual value minus the start lag value. It is directly coded by natural binary coding with 8 to 10 bits, depending on the sampling rates. Actual lag values are shown in Table 11.26, where “optP” denotes the actual prediction order for short-term prediction.

Table 11.26 – Search range of lag τ

search range of $\tau(i)$	start	end
Freq < 96 kHz	optP+1	optP+256
Freq \geq 96 kHz	optP+1	optP+512
Freq \geq 192 kHz	optP+1	optP+1024

11.6.4.2 LTP synthesis procedure

Provided both lag and gain parameters are decoded, the following recursive filtering operation is carried out:

$$d(i) = d(i) + \sum_{j=-2}^2 \rho(j) d(i - \tau + j)$$

For insuring perfect reconstruction, the process should be strictly defined. The pseudo-code for this filter at the decoder is as follows:

```
INT64 u;
for (smpl=0 ;smpl<end; smpl++)
{
    for (u=1<<6, tap=-2; tap<=2; tap++)
    {
        u += (INT64)LTPgain[tap]*d[smpl-lag+tap];
    }
    d[smpl] += (long)(u>>7);
}
```

Here, d is the residual signal (which is subsequently fed in the short-term synthesis filter, see section 11.6.3), $LTPgain$ is the gain value $\rho(i) \cdot 128$, and lag is the lag value τ .

For simple combination with the adaptive block switching, all values of the residual signal, $d(i)$ in the previous block are “0”. Associated with the synthesis filtering process above, there is a pseudo-code for the analysis filtering process at the encoder. Note this process should also be normative for the purpose of the perfect reconstruction. In this pseudo-code, the difference between the encoder and decoder appears in the last line: Input and output are common at the decoder, while they are different at the encoder.

```
INT64 u;
for (smpl=0 ;smpl<end; smpl++)
{
    for (u=1<<6, tap=-2; tap<=2; tap++)
    {
        u += (INT64)LTPgain[tap]*d[smpl-lag+tap];
    }
    dout[smpl] = d[smpl]-(long)(u>>7);
}
```

Here, d is the residual of short-term prediction, and $dout$ is the LTP residual.

11.6.5 RLS-LMS predictor mode

11.6.5.1 RLS-LMS predictor parameters

The parameters of the RLS-LMS predictor are signaled in `RLSLMS_extension()` when `ext_mode = 1`. The values of the predictor parameters are listed in the following tables.

Table 11.27 – RLS predictor order

index	RLS_order
0	0
1	2
2	4
3	6
4	8
5	10

6	12
7	14
8	16
9	18
10	20
11	22
12	24
13	26
14	28
15	30

Table 11.28 – Number of LMS predictors in cascade

index	LMS_stage
0	1
1	2
2	3
3	4
4	5
5	6
6	7
7	8

Table 11.29 – LMS predictor order

index	LMS_order
0	2
1	3
2	4
3	5
4	6
5	7
6	8
7	9
8	10
9	12
10	14
11	16
12	18
13	20

14	24
15	28
16	32
17	36
18	48
19	64
20	80
21	96
22	128
23	256
24	384
25	448
26	512
27	640
28	768
29	896
30	1024
31	reserved

Table 11.30 – LMS predictor stepsize

index	LMS_mu
0	1
1	2
2	3
3	4
4	5
5	6
6	7
7	8
8	9
9	10
10	11
11	12
12	13
13	14
14	15
15	16
16	18
17	20

18	22
19	24
20	26
21	28
22	30
23	35
24	40
25	45
26	50
27	55
28	60
29	70
30	80
31	100

When there is a change in the RLS or LMS filter order, the filter state (history buffers, weights, and the RLS inverse auto-correlation matrix P) needs to be reset. The next session describes how to reset and re-initialize the filter parameters. On detecting a filter order change, the decoder will automatically re-initialize its filters.

When the parameters for RLS-LMS predictor are not signalled, the parameters from the previous frame will be used.

11.6.5.2 RLS-LMS predictors

11.6.5.2.1 Initialization of the RLS_LMS predictor

The RLS and LMS adaptive filters is initialized at the start of the encoding or decoding process, and also at the start of each Random Access (RA) frame. The following pseudo code illustrates the initialization routine of the RLS_LMS predictor.

```
#define PFACTOR 115292150460684
#define LONG_MAX 0xffffffff
#define LONG_MIN 0x80000000
#define STEPSIZE 16777 // in 8.24 format for 0.001
#define ROUND1(x) ((long)(x+8)>>4)
#define ROUND2(x) ((INT64) ( (INT64) x + 1i64 )>>1)
```

RLS_filter_weight: Weights of the RLS filter
 LMS_filter_weight: Weights of the LMS filter
 P: Inverse auto-correlation matrix of the RLS filter
 TOTAL_FILTER_LEN: Total buffer size = DPCM_order + RLS_order+ LMS_order + Combiner_order

```
void predict_init()
{
  short i,j,ch;
  for (i=0; i<rls_filter_len; i++)
  {
    RLS_filter_weight[i] = 0; // RLS filter weight initialized to 0
  }
```

```

for (j=LMS_START;j<number of LMS_stages;j++)
{
    for (i=0; i<filter_len[j]; i++)
    {
        LMS_filter_weight[j][i] = 0; // clear LMS filters weight to 0
    }
}
for (i=0; i<number of filter stages; i++)
{
    w_final[i] = (long) 1<<24; // 1.0 in 7.24 format
}
// Joint-stereo RLS init
for (i=0; i<rls_filter_len*rls_filter_len;i++)
{
    P[rlsLms_ptr->channel][i]=0;
}
for (i=0; i<rls_filter_len; i++)
{
    P[i*rls_filter_len+i]=(INT64) (PFACTOR); // initialize to 0.0001 in 4.60 format
}
for(j=0;j<TOTAL_FILTER_LEN;j++) buf[j] = 0; // reset all lms, rls, dpcm, and linear combiner buffers
}

```

11.6.5.2.2 Filtering operation in the RLS_LMS predictor

The RLS-LMS predictor consists of a DPCM predictor, a RLS predictor, and various numbers of LMS predictors. In each of these predictors, a prediction is generated for every input sample by linearly combining the past samples. The DPCM predictor uses the previous sample $x[n-1]$ as the prediction of the current sample $x[n]$. The following pseudo code illustrates how the prediction of the current sample $x[n]$ is generated in an order- M LMS predictor.

```

INT64 y;
// Filter output
prediction = 0;
for (i=0;i<M;i++)
{
    prediction += ((INT64) w[i]) * x[n-i]; // 8.24 * 24.0 -> 32.24
}
prediction >= 20; // change y to 28.4 format
if (prediction > 0x7fffffff) y = 0x7fffffff; // clip to 24.4 format
if (prediction < -0x7fffffff) y = -0x7fffffff;

```

The following pseudo code illustrates how the prediction of the current sample $x[n]$ is generated in an order- M RLS predictor.

```

INT64 y;
// Filter output
prediction = 0;
for (i=0;i<M;i++)
{
    prediction += ((INT64) w[i]) * x[n-i]; // 14.16 * 24.0 -> 28.16
}
prediction >= 12; // change y to 28.4 format
if (prediction > 0x7fffffff) y = 0x7fffffff; // clip to 24.4
if (prediction < -0x7fffffff) y = -0x7fffffff;

```

The linear combiner multiplies weight $w_final[i]$ to the predictions of each predictor and the results are summed up. The result of the summation, after rounded to integer, is the output prediction of the RLS-LMS predictor. This prediction is subtracted from the current input sample to generate a prediction error. Note that the predictors and prediction errors are computed in 24.4 fixed-point format.

```

short i;
INT64 y,e;
INT64 temp;
long wchange;
prediction_final = 0;
for (i=0; i<STAGE; i++)
    prediction_final += (INT64) w_final[i]* prediction[i];
prediction_final >= 24 ;
assert(y<LONG_MAX && y>LONG_MIN);
e = (x<<4) /*convert to 24.4 or 16.4*/- prediction_final;

```

For the DPCM and RLS predictors, the linear combiner weights $w_final[i]$ are fixed at 0.001 (16777 in 8.24 format). The rest of the weights are updated using the following sign-sign LMS algorithm

```

if (prediction[i]*e >0)
{
    temp = w_final[i];
    if (temp<LONG_MAX) temp += STEPSIZE*LMS_stepsize;
    w_final[i] = (long) temp;
}
else if (prediction[j]*e<0)
{
    temp = w_final[i];
    if (temp>LONG_MIN) temp -= STEPSIZE*LMS_stepsize;
    w_final[i] = (long) temp;
}

```

The linear combiner weights are clipped at values of LONG_MAX and LONG_MIN (0x7fffffff and 0x80000000 in 8.24 format, respectively).

In the encoder, the prediction error is produced by subtracting the rounded (to 24.0 format) prediction $prediction_final$ from the input PCM sample x as follows:

$residual = x - (\text{long})((prediction_final+8)>>4);$

where $residual$ is the prediction error which will be further coded by the entropy coder.

In the decoder, a reverse process is performed to restore the original PCM sample

$x = residual + (\text{long})((prediction_final+8)>>4);$

In the RLS-LMS predictor, the DPCM predictor has fixed order and weight of 1. The weights of the RLS and LMS predictors are updated continuously until they are resetted due to there is a RA frame or a change of filter parameters.

11.6.5.2.3 Joint-stereo RLS and mono RLS

A single channel element (SCE) is processed by the mono RLS predictor whose history buffer is updated from samples within the channel.

A channel pair element (CPE) is processed by the joint-stereo RLS predictor which generates predictions of each channel by using samples from both channels. Therefore, the history buffers of the predictor contain

interleaved past samples from both the left and the right channels. The joint-stereo RLS predictor maintains two sets of P matrix and filter weights, one for each channel. If the Joint-Stereo flag is not set in the ALS header, mono RLS is used for each independent channel. For a CPE, if both channels contain only constant or zero, the prediction filter is bypassed for that frame.

When *mono_block* is set to 1 for a CPE, it is coded as two individual channels L and L-R, where the L channel is coded as a SCE by the mono predictor (DPCM + mono_RLS + LMS), whereas samples of the L-R channel are directly sent to the entropy coder.

11.6.5.2.4 Adaptation of RLS filter weights

The RLS filter weights are updated by the following pseudo code, which has three main stages: computing the gain vector $k[i]$, updating the filter weight $w[i]$, and updating the matrix P.

P: Inverse auto-correlation matrix
 x: Input PCM sample
 y: Prediction
 w: Filter weights
 M: Filter order
 bufl: History buffer containing the past M input samples
 lambda: Forgetting factor

```

/* Routine to re-initialize the P matrix */
void reinit_P(INT64 *Pmatrix)
{
  short i;
  // Joint-stereo RLS init
  for (i=0; i<rls_filter_len*rls_filter_len;i++)
  {
    Pmatrix[i]=0;
  }
  for (i=0; i<rls_filter_len; i++)
  {
    Pmatrix[i*rls_filter_len+i]=(INT64) (PFACTOR); // initialize to 0.0001 in 4.60 format
  }
}

void UpdateRLSFilter(long *x, long y, W_TYPE *w, short M, long *bufl, P_TYPE *P)
{
  short i,j,shift,vscale,dscale;
  INT64 k[256];
  INT64 wtemp,wtemp2;
  INT64 htemp,ir,ltemp,htemp1,htemp2;
  long vl[256];
  UINT64 uthemp,ltemp1;
  long lr,e,kscale,shifted_e;

  // get the error by subtracting current sample x with the predictor y
  e = (*x-y);

  // Step1. Compute gain vector k
  MulMtxVec(P, bufl, M, vl, &vscale); // (vl, vscale) = matrix P * matrix bufl

  wtemp = MulVecVec(bufl, vl, M, &dscale); // wtemp = bufl
  assert((vscale+dscale)<64);
  i = 0;

  while(wtemp> LONG_MAX/4 && wtemp!=0) {wtemp>>=1;i++;}
  i += vscale + dscale;
}
  
```

```

if (i<=60)
    wtemp += (1i64<<(60-i));
else
{
    reinit_P(P); // in case P is round to zero, re-initialize P
}
wtemp2 = wtemp;
assert(i<90);
if (wtemp == 0)
{
    ir=1L<<30;
}
else if ((90-i)>62)
{
    shift = 90-(i)-62;
    ir = (1i64<<62)/ (wtemp2) ;
    if (shift>32)
        ir = 1L<<30;
    else if (shift>=0)
        ir <=> shift;
}
else // i>28
{
    if ((90-i)>32)
        ir = (1i64<<(90-(i)))/(wtemp2);
}
lr = (long) ir;
htemp1 = 0;
for (i=0; i<M; i++)
{
    htemp = (INT64) vl[i] * lr;
    if (vscale>=12)
    {
        k[i] = htemp<<(vscale-12);
        k[i] = ROUND2(k[i]);
    }
    else
    {
        k[i] = htemp>>(11-vscale);
        k[i] = ROUND2(k[i]);
    }
    htemp1 |= (k[i]>0 ? k[i]:-k[i]);
}
dscale = fast_bitcount(htemp1); // count how many significant bit htemp1 has
if (dscale>30)
{
    dscale -= 30;
    for (i=0; i<M; i++)
    {
        k[i] >= dscale;
    }
}
else
{
    dscale = 0;
}

// Step2. Update weight
shifted_e = e>>3;
for (i=0; i<M; i++)

```

```

{
    htemp1 = (INT64) k[i] * shifted_e;
    htemp = (htemp1>>(30-dscale));
    wtemp = w[i] + ROUND2(htemp);
    w[i] = (long) wtemp;
}
vscale += dscale;

// Step3. Update P matrix
for (i=0; i<M; i++) // Lower triangular
    for (j=0; j<=i; j++)
    {
        htemp2 = (INT64) k[i] * vl[j];
        wtemp = htemp2>>(14-vscode);
        P[i*M+j] -= wtemp;
        if (P[i*M+j]>=_I64_MAX/2) { reinit_P(P); break; }
        if (P[i*M+j]<=_I64_MIN/2) { reinit_P(P); break; }
        wtemp = P[i*M+j]/lambda;
        P[i*M+j] += wtemp;
    }
for (i=1; i<M; i++) // Upper triangular
    for (j=0; j<i; j++)
        P[j*M+i] = P[i*M+j];
// Buffer update
buffer_update(*x>>4,bufI,M);
*x = (long) e;
}

```

The following routine multiplies an input vector x to the matrix P and generates an output vector yi , which is normalized to 28.0 format with a scale factor $vscale$.

```

void MulMtxVec(P_TYPE *P, long *x, short M, long *yi, short *vscale)
{
    P_TYPE *ptr;
    short i,j,cc,pscale,nscale;
    INT64 htemp,yh[256],ttemp,imax,htemp1,PT[500],ya[256],ttemp1;
    UINT64 yl[256],ltemp,ltemp1;
    *vscale = 0;
    imax = 0;
    htemp1 = 0;
    for(i=0;i<M;i++)
    {
        ptr = P;
        ptr += i*M;
        for(j=0;j<=i;j++)
        {
            htemp1 |= (*ptr> 0 ? *ptr : - *ptr);
            ptr++;
        }
    }
    pscale = 63-fast_bitcount(htemp1); // bit_count counts number of significant bits htemp1 has
    ttemp1 = 0;
    for (i=0; i<M; i++)
    {
        ptr = P;
        ptr += i*M;
        ya[i]=0;
        for (j=0; j<M; j++)
        {

```

```

        ya[i] += (INT64) (((*ptr++<<pscale)+0x0000000080000000i64)>>32) * x[j];
    }
    ttemp1 |= (ya[i]>0 ? ya[i]:-ya[i]);
}
nscale = fast_bitcount(ttemp1);
if (nscale>28)
{
    nscale -= 28;
    for(i=0;i<M;i++)
    {
        ya[i]>>=nscale;
        yi[i] = ya[i];
    }
    *vscale = nscale-pscale;
}
else
{
    nscale -=28;
    for(i=0;i<M;i++)
    {
        yi[i] = ya[i]; // & 0x00000000ffffffffi64;
    }
    *vscale = -pscale;
}
}

```

The following routine calculates the inner product of two vector x and y and normalizes the output value z to 60.0 format with a scale factor $scale$.

```

INT64 MulVecVec(long *x, long *y, short M, short *scale)
{
    short i;
    INT64 z,zh,temp;
    *scale = 0;
    zh = 0;
    for (i=0; i<M; i++)
    {
        zh += (INT64) (y[i])* x[i];
    }
    temp = zh ;
    temp = (temp>0 ? temp:-temp); // drop the sign
    *scale = fast_bitcount(temp);
    if (*scale>28)
    {
        *scale -= 28; // this is the amount of excess 64 bit
        assert(*scale<32);
        z = (zh<<(32-(*scale-1)));
        z = ROUND2(z);
    }
    else
    {
        z = (zh<<32); // shift to upper 32 bit
    }
    assert(z<_l64_MAX/2 && z>_l64_MIN/2);
    return(z);
}

```

11.6.5.2.5 Adaptation of LMS filter weights

The LMS filter weights are updated by the normalized-LMS algorithm (NLMS). The pseudo code is given below.

x: Input PCM sample
 w: Filter weights
 M: Filter order
 buf: History buffer containing the past M input samples
 mu: Stepsize
 pow: Power of the samples in the history buffer

```

// NLMS weight update
void update_predictor(long *x, long y, BUF_TYPE *buf, W_TYPE *w, short M, short mu, INT64 *pow)
{
  short i,j;
  INT64 fact;
  INT64 wtemp,e,wtemp1;
  long temp;

  // Calculation of Prediction error
  e = (*x - y); // y is 24.4 format change x to 24.4

  // Weight update

  wtemp1 = wtemp = ((INT64) mu * (*pow>>7));
  i = 0;
  while(wtemp> LONG_MAX) {wtemp>>=1;i++;}
  fact = ((INT64) e<<(29-i))/(INT64)((wtemp1 + 1)>>i);

  for (j=0; j<M; j++)
  {
    w[j] = w[j] + (long) (((INT64) buf[j]* (INT64) fact + 0x8000)>>16);
  }

  // NLMS power update
  temp = (*x)>>4; // x is in 28.4 format need to change to 28.0
  *pow -= (INT64) buf[0] * (INT64) buf[0];
  *pow += (INT64) temp * temp;
  if (*pow>_I64_MAX) *pow = _I64_MAX;

  // Buffer update – add in the current sample temp
  buffer_update(temp,buf,M);

  // Predictor output
  *x = (long) e; // overwrite the current sample with the error for next filter stage
}
  
```

11.6.5.3 Random Access in RLSLMS mode

In the Random Access (RA) frame, the predictor resets all its filters to their initial states to ensure synchronized encoding and decoding. For a RA frame of length M, the first M/32 samples are not updated into the LMS history buffer. The adaptation of the LMS filter weights starts only after the first M/32 samples. In an RA frame, the RLS filter uses the forgetting factor *RLS_lambda_ra* for the first 300 samples, after that, the forgetting factor *RLS_lambda* is used.

11.6.6 Coded Residual

There are two possible modes for transmission of the prediction residual: A fast encoding scheme employing simple Rice codes (see subclause 11.6.6.1), and a more complex and efficient scheme using block Gilbert-Moore codes (BGMC, see subclause 11.6.6.2).

11.6.6.1 Rice Codes

When the *bgmc_mode* flag in the ALSSpecificConfig is set to 0, the residual values are entropy coded using Rice codes. The chosen syntax for codeword generation is specified in the following.

A Rice code is defined by a parameter $s \geq 0$. For a given value of s , each codeword consists of a p -bit prefix and an s -bit sub-code. The prefix is signalled using $p-1$ "1"-bits and one "0"-bit, with p depending on the coded value. For a signal value x and $s > 0$, $p-1$ is calculated as follows ("÷" means integer division without remainder):

$$p-1 = \begin{cases} x \div 2^{s-1} & \text{for } x \geq 0 \\ (-x-1) \div 2^{s-1} & \text{for } x < 0 \end{cases}$$

For $s = 0$, we use a modified calculation:

$$p-1 = \begin{cases} 2x & \text{for } x \geq 0 \\ -2x-1 & \text{for } x < 0 \end{cases}$$

The sub-code for $s > 0$ is calculated as follows:

$$sub = \begin{cases} x - 2^{s-1}(p-1) + 2^{s-1} & \text{for } x \geq 0 \\ (-x-1) - 2^{s-1}(p-1) & \text{for } x < 0 \end{cases}$$

For $s = 0$ there is no sub-code but only the prefix, thus the prefix and the codeword are identical. Permitted values are $s = 0 \dots 15$ for a sample resolution ≤ 16 bits, and $s = 0 \dots 31$ for a sample resolution > 16 bits.

Table 11.31 and Table 11.32 show examples for the Rice code with $s = 4$. Table 11.33 shows the special Rice code with $s = 0$.

Table 11.31 – Rice code with $s = 4$. The xxxx bits contain the 4-bit sub-code sub

Values	p	Prefix	Codeword
-8...+7	1	0	0xxxx
-16...-9; +8...+15	2	10	10xxxx
-24...-17; +16...+23	3	110	110xxxx
-32...-25; +24...+31	4	1110	1110xxxx
-40...-33; +32...+39	5	11110	11110xxxx

Table 11.32 – Sub-codes of the Rice code with $s = 4$ for the first three prefixes

Values ($p = 1$)	Values ($p = 2$)	Values ($p = 3$)	sub-code (xxxx)
-8	-16	-24	0111
-7	-15	-23	0110

-6	-14	-22	0101
-5	-13	-21	0100
-4	-12	-20	0011
-3	-11	-19	0010
-2	-10	-18	0001
-1	-9	-17	0000
0	8	16	1000
1	9	17	1001
2	10	18	1010
3	11	19	1011
4	12	20	1100
5	13	21	1101
6	14	22	1110
7	15	23	1111

Table 11.33 – "Special" Rice code with $s = 0$ (prefix and codeword are identical)

Values	p	Prefix	Codeword
0	1	0	0
-1	2	10	10
+1	3	110	110
-2	4	1110	1110
+2	5	11110	11110

For each block of residual values, either all values can be encoded using the same Rice code, or, if the sb_part flag in the file header is set, the block can be divided into four sub-blocks, each encoded with a different Rice code. In the latter case, the ec_sub flag in the block header indicates whether one or four blocks are used.

While the parameter $s[i = 0]$ of the first sub-block is directly transmitted with either 4 bits (resolution ≤ 16 bits) or 5 bits (resolution > 16 bits), only the differences of following parameters $s[i > 0]$ are transmitted. These differences are additionally encoded using appropriately chosen Rice codes again (see Table 11.34).

Table 11.34 – Coding of Rice code parameters $s[i]$

Code parameter ($i = \text{sub-block index}$)	Difference	Rice code parameter used for differences
$s[i] (i > 0)$	$s[i] - s[i-1]$	0

There are different ways to determine the optimal index s for a given set of data. It is up to the encoder to select suitable Rice codes depending on the statistics of the residual.

11.6.6.2 BGMC coding mode

When the *bgmc_mode* flag in the file header is set to 1, the residual values are split into *MSB*, *LSB* and *tail* components, which are then encoded using block Gilbert-Moore, fixed-length, and Rice codes correspondingly.

Furthermore, a different sub-block partition scheme is used. If the *sb_part* flag in the file header is set, each block can be divided into 1, 2, 4, or 8 sub-blocks, where the actual number is indicated by a 2-bit *ec_sub* field in the block header. If *sb_part* is not set, each block can only be divided into 1 or 4 sub-blocks, and the actual number is indicated by a 1-bit *ec_sub* field.

The subsequent sections 11.6.6.2.1 – 11.6.6.2.4 describe details of the BGMC coding process.

11.6.6.2.1 Additional Parameters

In addition to the code parameter *s* (used to construct Rice codes), the BGMC encoder/decoder relies on the following quantities:

The number of lowest-significant bits (LSBs) *k* of residuals to be transmitted directly:

$$k = \begin{cases} 0, & \text{if } s \leq B \\ s - B, & \text{if } s > B \end{cases}$$

where *s* is the Rice parameter, and *B* is a parameter depending on the sub-block size *N*:

$$B = (\lceil \log_2 N \rceil - 3) \gg 1;$$

where $0 \leq B \leq 5$ (values out of bounds are clipped to the bounds). The number of missing (in accessing frequency tables) bits *delta*:

$$\text{delta} = 5 - s + k,$$

and finally, the index of a frequency table *sx* to be used for encoding/decoding of MSBs.

The parameter *sx* is transmitted in addition to *s* for each sub-block, where the 'complete' BGMC parameter can be represented as $S = 16 \cdot s + sx$. Similar to the Rice coding mode, the first parameter is directly transmitted, while for subsequent parameters only encoded differences are transmitted (see Table 11.35).

Table 11.35 – Coding of BGMC code parameters $S[i] = 16 \cdot s[i] + sx[i]$

Code parameter (i = sub-block index)	Difference	Rice code parameter used for differences
$S[i]$ ($i > 0$)	$S[i] - S[i-1]$	2

11.6.6.2.2 Splitting Residual Values on MSBs, LSBs, and Tails

The process of obtaining sign-removed and clipped MSB values, LSBs or tails corresponding to the residual samples (*res[i]*) can be described as follows:

```

for (i = 1; i <= N; i++)
{
    long msbi = res[i] >> k; // remove lsbs
    if (msbi >= max_msb[sx][delta]) { // positive tail
        msb[i] = tail_code[sx][delta];
        tail[i] = res[i] - (max_msb[sx][delta] << k);
    }
}

```

```

} else
if (msbi <= -max_msb[sx][delta]) {           // negative tail
    msb[i] = tail_code[sx][delta];
    tail[i] = res[i] + ((max_msb[sx][delta] - 1) << k);
} else {                                         // normal msb range
    if (msbi >= 0) msbi = msbi * 2;
    else           msbi = -msbi * 2 -1;    // remove sign
    if (msbi >= tail_code[sx][delta])
        msbi++;
    msb[i] = msbi;                           // msb and lsb values
    lsb[i] = res[i] & ((1<<k)-1);        // to encode
}
}
}

```

The maximum absolute values of MSBs and tail codes used in this algorithm (arrays `max_msb[]` and `tail_code[]` correspondingly) are specified in the following tables.

Table 11.36 – Maximum/minimum values of residual MSBs

<i>delta</i> sx	0	1	2	3	4	5
0	±64	±32	±16	±8	±4	±2
1	±64	±32	±16	±8	±4	±2
2	±64	±32	±16	±8	±4	±2
3	±96	±48	±24	±12	±6	±3
4	±96	±48	±24	±12	±6	±3
5	±96	±48	±24	±12	±6	±3
6	±96	±48	±24	±12	±6	±3
7	±96	±48	±24	±12	±6	±3
8	±96	±48	±24	±12	±6	±3
9	±96	±48	±24	±12	±6	±3
10	±96	±48	±24	±12	±6	±3
11	±128	±64	±32	±16	±8	±4
12	±128	±64	±32	±16	±8	±4
13	±128	±64	±32	±16	±8	±4
14	±128	±64	±32	±16	±8	±4
15	±128	±64	±32	±16	±8	±4

Table 11.37 - Tail Codes.

<i>delta</i> sx	0	1	2	3	4	5
0	74	44	25	13	7	3
1	68	42	24	13	7	3
2	58	39	23	13	7	3
3	126	70	37	19	10	5

4	132	70	37	20	10	5
5	124	70	38	20	10	5
6	120	69	37	20	11	5
7	116	67	37	20	11	5
8	108	66	36	20	10	5
9	102	62	36	20	10	5
10	88	58	34	19	10	5
11	162	89	49	25	13	7
12	156	87	49	26	14	7
13	150	86	47	26	14	7
14	142	84	47	26	14	7
15	131	79	46	26	14	7

The inverse (decoding) process, reconstructing the original residual samples ($res[i]$) based on their MSBs, LSBs or tails can be described as follows:

```

for (i = 1; i <= N; i++) {
{
    if (msb[i] == tail_code[sx][delta]) {
        if (tail[i] >= 0)          // positive tail
            res[i] = tail[i] + (abs_max_x) << k;
        else                      // negative tail
            res[i] = tail[i] - (abs_max_x - 1) << k;
    } else {
        int msbi = msb[i];
        if (msbi > tail_code[sx][delta])
            msbi --;           // skip tail code
        if (msbi & 1)
            msbi = (-msbi -1)/2; // remove sign
        else
            msbi = msbi/2;
        res[i] = (msbi << k) | lsb[i]; // add lsb
    }
}
}

```

11.6.6.2.3 Encoding and Decoding of MSBs

The clipped MSBs of the residual samples are block-coded using Gilbert-Moore codes constructed for a distribution (cumulative frequency table) indexed by the parameter sx .

The encoding process consists of a) initialising the state of the block Gilbert-Moore (arithmetic) encoder, b) sequential encoding of all MSB values in all sub-blocks, and c) flushing the state of the encoder.

C-language specifications of the corresponding functions of the encoder are given below.

```

#define FREQ_BITS 14 // # bits used by freq. counters
#define VALUE_BITS 18 // # bits used to describe code range
#define TOP_VALUE 0x3FFF // largest code value
#define FIRST_QTR 0x10000 // first quarter
#define HALF 0x20000 // first half
#define THIRD_QTR 0x30000 // third quarter

```

```

// encoder state variables:
static unsigned long high, low, bits_to_follow;

// start encoding:
void bgmc_start_encoding (void)
{
    high = TOP_VALUE;
    low = 0;
    bits_to_follow = 0;
}

// sends a bit followed by a sequence of opposite bits:
void put_bit_plus_follow (unsigned long bit)
{
    put_bit (bit);
    while (bits_to_follow) {
        put_bit (bit ^ 1);
        bits_to_follow--;
    }
}

// encodes a symbol using Gilbert-Moore code for
// a distribution s_freq[] subsampled by delta bits:
void bgmc_encode (unsigned long symbol, long delta, unsigned long *s_freq)
{
    unsigned long range = high -low +1;
    high=low+((range*s_freq[symbol]<<delta]-(1<<FREQ_BITS))>>FREQ_BITS);
    low =low+((range*s_freq[(symbol+1)<< delta])>>FREQ_BITS);

    for ( ; ; ) {
        if (high < HALF) {
            put_bit_plus_follow (0, p);
        } else if (low >= HALF) {
            put_bit_plus_follow (1, p);
            low -= HALF;
            high -= HALF;
        } else if (low >= FIRST_QTR && high < THIRD_QTR) {
            bits_to_follow += 1;
            low -= FIRST_QTR;
            high -= FIRST_QTR;
        } else
            break;
        low = 2 * low;
        high = 2 * high + 1;
    }
}

// Finish the encoding:
static void bgmc_finish_encoding ()
{
    bits_to_follow += 1;
    if (low < FIRST_QTR) put_bit_plus_follow (0,p);
    else put_bit_plus_follow (1,p);
}

```

C-language specifications of the corresponding functions of the block Gilbert-Moore decoder are given below.

```

// decoder state variables:
static unsigned long high, low, value;

// start decoding:
void bgmc_start_decoding (void)
{
    high = TOP_VALUE;
    low = 0;
    value = get_bits(VALUE_BITS);
}

// decodes a symbol using Gilbert-Moore code for
// a distribution s_freq[] subsampled by delta bits:
unsigned long bgmc_decode (long delta, unsigned long *s_freq)
{
    unsigned long range, target, symbol;
    range = high - low + 1;
    target = (((value - low + 1) << FREQ_BITS) - 1) / range;
    symbol = 0;
    while (s_freq [(symbol+1) << delta] > target)
        symbol++;
    high=low+((range*s_freq[symbol<<delta]-(1<<FREQ_BITS))>>FREQ_BITS);
    low=low+((range*s_freq[(symbol+1)<<delta])>>FREQ_BITS);
    for ( ; ; ) {
        if (high < HALF) ;
        else if (low >= HALF) {
            value -= HALF;
            low -= HALF;
            high -= HALF;
        } else if (low >= FIRST_QTR && high < THIRD_QTR) {
            value -= FIRST_QTR;
            low -= FIRST_QTR;
            high -= FIRST_QTR;
        } else
            break;
        low = 2 * low;
        high = 2 * high + 1;
        value = 2 * value + get_bit ();
    }
    return symbol;
}

// Finish decoding:
void bgmc_finish_decoding ()
{
    scroll_bitstream_position_back(VALUE_BITS-2);
}

```

The cumulative frequency tables (*s_freq[]* arrays) used by the above algorithms for encoding/decoding of residual MSBs are listed below. The appropriate (within each sub-block) table is selected using parameter *sx*.

Table 11.38 – Cumulative frequency tables used by the BGMC encoder/decoder

#	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	16384	16384	16384	16384	16384	16384	16384	16384	16384	16384	16384	16384	16384	16384	16384	16384
1	16066	16080	16092	16104	16116	16128	16139	16149	16159	16169	16177	16187	16195	16203	16210	16218
2	15748	15776	15801	15825	15849	15872	15894	15915	15934	15954	15970	15990	16006	16022	16036	16052
3	15431	15473	15510	15546	15582	15617	15649	15681	15709	15739	15764	15793	15817	15842	15863	15886
4	15114	15170	15219	15268	15316	15362	15405	15447	15485	15524	15558	15597	15629	15662	15690	15720
5	14799	14868	14930	14991	15050	15107	15162	15214	15261	15310	15353	15401	15441	15482	15517	15554
6	14485	14567	14641	14714	14785	14853	14919	14981	15038	15096	15148	15205	15253	15302	15344	15389
7	14173	14268	14355	14439	14521	14600	14677	14749	14816	14883	14944	15009	15065	15122	15172	15224
8	13861	13970	14069	14164	14257	14347	14435	14517	14594	14670	14740	14813	14878	14942	15000	15059
9	13552	13674	13785	13891	13995	14096	14195	14286	14373	14458	14537	14618	14692	14763	14828	14895
10	13243	13378	13501	13620	13734	13846	13955	14055	14152	14246	14334	14423	14506	14584	14656	14731
11	12939	13086	13219	13350	13476	13597	13717	13827	13933	14035	14132	14230	14321	14406	14485	14567
12	12635	12794	12938	13081	13218	13350	13479	13599	13714	13824	13930	14037	14136	14228	14314	14403
13	12336	12505	12661	12815	12963	13105	13243	13373	13497	13614	13729	13845	13952	14051	14145	14240
14	12038	12218	12384	12549	12708	12860	13008	13147	13280	13405	13529	13653	13768	13874	13976	14077
15	11745	11936	12112	12287	12457	12618	12775	12923	13065	13198	13330	13463	13585	13698	13808	13915
16	11452	11654	11841	12025	12206	12376	12542	12699	12850	12991	13131	13273	13402	13522	13640	13753
17	11161	11373	11571	11765	11956	12135	12310	12476	12636	12785	12933	13083	13219	13347	13472	13591
18	10870	11092	11301	11505	11706	11894	12079	12253	12422	12579	12735	12894	13037	13172	13304	13429
19	10586	10818	11037	11250	11460	11657	11851	12034	12211	12376	12539	12706	12857	12998	13137	13269
20	10303	10544	10773	10996	11215	11421	11623	11815	12000	12173	12343	12518	12677	12824	12970	13109
21	10027	10276	10514	10746	10975	11189	11399	11599	11791	11972	12150	12332	12499	12652	12804	12950
22	9751	10008	10256	10497	10735	10957	11176	11383	11583	11772	11957	12146	12321	12480	12639	12791
23	9483	9749	10005	10254	10500	10730	10956	11171	11378	11574	11766	11962	12144	12310	12475	12633
24	9215	9490	9754	10011	10265	10503	10737	10959	11173	11377	11576	11778	11967	12140	12312	12476
25	8953	9236	9508	9772	10034	10279	10521	10750	10971	11182	11388	11597	11792	11971	12149	12320
26	8692	8982	9263	9534	9803	10056	10305	10541	10769	10987	11200	11416	11617	11803	11987	12164
27	8440	8737	9025	9303	9579	9838	10094	10337	10571	10795	11015	11237	11444	11637	11827	12009
28	8189	8492	8787	9072	9355	9620	9883	10133	10373	10603	10830	11059	11271	11471	11667	11854
29	7946	8256	8557	8848	9136	9407	9677	9933	10179	10414	10647	10882	11100	11307	11508	11701
30	7704	8020	8327	8624	8917	9195	9471	9733	9985	10226	10465	10706	10930	11143	11349	11548
31	7472	7792	8103	8406	8703	8987	9268	9536	9793	10040	10285	10532	10762	10980	11192	11396
32	7240	7564	7879	8188	8489	8779	9065	9339	9601	9854	10105	10358	10594	10817	11035	11244
33	7008	7336	7655	7970	8275	8571	8862	9142	9409	9668	9925	10184	10426	10654	10878	11092
34	6776	7108	7431	7752	8061	8363	8659	8945	9217	9482	9745	10010	10258	10491	10721	10940
35	6554	6888	7215	7539	7853	8159	8459	8751	9029	9299	9568	9838	10091	10330	10565	10790
36	6333	6669	7000	7327	7645	7955	8260	8557	8842	9116	9391	9666	9925	10169	10410	10640
37	6122	6459	6792	7123	7444	7758	8067	8369	8658	8937	9218	9497	9761	10011	10257	10492
38	5912	6249	6585	6919	7244	7561	7874	8181	8475	8759	9045	9328	9598	9853	10104	10344
39	5711	6050	6387	6724	7051	7371	7688	7998	8297	8585	8876	9163	9438	9697	9953	10198
40	5512	5852	6190	6529	6858	7182	7502	7816	8120	8411	8707	8999	9278	9542	9802	10052
41	5320	5660	5998	6339	6671	6997	7321	7638	7946	8241	8541	8837	9120	9389	9654	9908
42	5128	5468	5807	6150	6484	6812	7140	7460	7773	8071	8375	8675	8963	9236	9506	9764
43	4947	5286	5625	5970	6305	6635	6965	7288	7604	7906	8213	8517	8809	9086	9359	9622